

Multi-choice stochastic transportation problem involving Weibull distribution

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Abstract. This paper explains the important role in application of stochastic distribution and multi-choice framework on the field of transportation environment. The purpose of this paper is to provide a solution procedure to multi-choice stochastic transportation problem involving the parameters as supply and demand of Weibull distribution and cost coefficients of a single criterion of minimization of objective function which are multi-choice in nature. At first, all stochastic constraints are transformed into deterministic constraints by using the stochastic approach. Recently, Mahapatra et al. [14] have proposed a methodology to transfer the multi-choice stochastic transportation problem to an equivalent mathematical programming model which can accumulate a maximum of eight choices on the cost coefficients of the objective function. In this paper, a generalized transformation technique is also present to discuss the two types of transformation technique. Using any one of the transformation technique, the decision maker can handle a parameter of the cost coefficients of objective function with finite number of choice associated with additional restriction for obtaining the equivalent deterministic form. Finally, a numerical example is provided to validate the theoretical development and solution procedure.

Keywords: Multi-choice programming; stochastic programming; weibull distribution; transportation problem; transformation technique; mixed-integer programming

AMS Classification: 90C08; 90C15; 990C11

1. Introduction

A transportation problem refers to a class of linear programming problems that involves selection of most economical shipping routes for transfer of a uniform commodity from a number of sources to a number of destinations. A stochastic transportation model in which the constraints are stochastic in nature and the cost coefficients are multi choice type is considered. These two contributions are mainly responsible for the development of this transportation models. The above models deals with transportation of a product available at several sources to a number of different destinations. Each shipping sources has a certain capacity and each destination has a certain requirement associated with a certain cost

of shipping from sources to the destinations. The objective is to minimize the cost of transportation while meeting the requirements at the destinations. Transportation problems may also involve movement of product from plants to warehouses, warehouses to warehouses, warehouses to retailers and retailers to customers.

In transportation problem, there are in m sources and n destinations. Let C_{ij}^k of the k -th objective function could represent the unit of transportation cost for transporting the unit from i -th ($i = 1, 2, \dots, m$) origin to j -th ($j = 1, 2, \dots, n$) destination, x_{ij} is the quantity shipped from the i -th origin to j -th destination, a_i is the supply available at origin i and b_j is the destination j

In such a situation, all these parameters of all

constraints are defined as random variables to follow Weibull distribution. Thus there exists multi-choice penalty criteria in the cost coefficients of transportation which leads to the research work on multi-choice stochastic transportation problem. Most of real world problems of practical importance are modeled nowadays with multi-choice parameters. Hitchcock [11] first presented a study entitled "The Distribution of a Product from Several Sources to Numerous Localities". The presentation is regarded as the first important contribution to the solution of transportation problems. Koopmans [12] presented a study called "Optimum Utilization of the Transportation System". These two contributions are mainly responsible for the development of transportation models which involve a number of shipping sources and a number of destinations.

In real-world application, it is very difficult to know all the information about the input parameters of the mathematical programming model because relevant data are in existent or scarce, difficult to obtain or to estimate, the system is subject to changes, and so forth, that is, input parameters are uncertain. One of the best ways of modeling these uncertainties in the form of mathematical programming is known as stochastic programming. It is widely used in several research areas such as agriculture, capacity planning, finance, forestry, military, production control and scheduling, telecommunication, transportation, environmental management planning etc. Goicoechea et al. [10] discussed the deterministic equivalents for some probabilistic programming involving normal and other distributions. Mahapatra et al. [13], have presented the solution procedure of multi-objective stochastic transportation problem incorporating normal distribution with joint constraints. The mathematical formula of the Weibull distribution is defined as follows: a random variable x is said to be Weibull distributed if its probability density function is given by

$$f(x; \alpha, \beta) = \frac{\alpha}{\beta^\alpha} x^{\alpha-1} e^{-\left(\frac{x}{\beta}\right)^\alpha};$$

$$x \geq 0 \text{ and } \alpha > 0, \beta > 0, \quad (1)$$

where α and β are the shape and scale parameters. The Weibull distribution has been found to be useful for describing cost times and lifetimes in reliability applications. It is distribution that received maximum attention in the past few decades. Weibull distribution may be a good choice to describe the data on lifetimes or strength data, in some practical situations it

fits worse than its competitions. In this manner, it is applied in risk analysis, actuarial science and engineering. Furthermore, the Weibull distribution has applications in medical, biological, transportation planning and earth sciences etc. Weibull Wallodi [17], a Sweden physicist in 1950's, first introduced the Weibull distribution, it has become a useful data treatment method in reliability studies of materials and electronic devices. The Weibull distribution is practically and theoretically applicable to the studies of estimation of the future probability under a certain loading by Fok [9].

Multi-choice programming is a mathematical programming problem, in which the decision maker is allowed to set multiple number of choices for a parameter. In recent years, methods of multi-choice stochastic optimization become increasingly important in solving scientifically decision making problems arising in economics, industry, health care, transportation, agriculture, military, engineering and technology. Biswal and Acharya [2] proposed transformation techniques to transform multi-choice linear programming problem to an equivalent mathematical model in which constraints are associated with multi-choice parameters. In 2007, Chang [4], [5] presented multi-choice goal programming model with limited number of choices for a parameter with multiplicative terms of binary variables using continuous variable. In other paper Chang [6], he has also proposed a revised method for multi-choice goal programming model which does not involve multiplicative terms of binary variables to model the multiple aspiration levels. Chang et al. [7] discussed the present situation of commutative business environment. Hence to find ways maximize profit and to minimize total costs, group pricing discrimination strategy has become an important issue for decision makers. Biswal and Acharya [3] discussed the solving for probabilistic programming problem involving multi-choice parameters. Acharya et al. [1] presented a generalized form of new transformation technique of multi-choice linear programming problem. Liao [8] have proposed an alternative method for solving the multi-segment goal programming problems with two contributions: (1) the alternative method represents a linear form of multi-segment goal programming which can easily be solved by common linear programming sties, and (2) the alternative approach does not involve multiplicative terms of binary variables, this leads to more efficient use of multi-segment goal programming and is easily understood by industrial participants. Ravindran et

al. [15] have presented a mathematical model in which an appropriate constraint is to be chosen using binary variables. The present paper considers both randomness and multi-choice simultaneously in the application area of transportation planning frame work. Two different types of stochastic inequality constraints are associated with the problem where the random variables follow Weibull distribution. The cost coefficients of the objective function are multi-choice type, where a generalized transformation technique is established for transforming the multi-choice transportation problem to an equivalent mathematical programming model. Using any one of these transformation techniques, the transformed model can be derived. Binary variable and additional restrictions are introduced to formulate a non-linear mixed integer programming model. In order to solve the present problem, a new methodology has been proposed to solve multi-choice stochastic transportation problem. The remainder of the paper is organized as follows: following the introduction in Section 1, mathematical model of multi-choice stochastic transportation problem involving Weibull distribution is presented in Section 2. The generalized transformation techniques to derive equivalent mathematical models of multi-choice stochastic transportation problem involving Weibull distribution are presented in Section 3. In order to verify the proposed transformation techniques, a case study is presented in Section 4. Finally, conclusions and points towards directions for future research are presented in Section 5 respectively.

2. Mathematical Model

In this paper, a mathematical model for multi-choice stochastic transportation problem involving Weibull distribution is considered as follows:

Model 1

$$\min : z = \sum_{i=1}^m \sum_{j=1}^n \{C_{ij}^1, C_{ij}^2, \dots, C_{ij}^k\} x_{ij},$$

$$k = 1, 2, \dots, K \quad (2)$$

$$\text{subject to} \quad \Pr \left(\sum_{j=1}^n x_{ij} \leq s_i \right) \geq 1 - \gamma_i,$$

$$i = 1, 2, \dots, m \quad (3)$$

$$\Pr \left(\sum_{i=1}^m x_{ij} \geq d_j \right) \geq 1 - \delta_j,$$

$$j = 1, 2, \dots, n \quad (4)$$

$$x_{ij} \geq 0, \quad \forall i \text{ and } j \quad (5)$$

where $0 < \gamma_i < 1, \forall i$ and $0 < \delta_j < 1, \forall j$.

It is assumed that s_i ($i = 1, 2, \dots, m$) and d_j ($j = 1, 2, \dots, n$) are Weibull random variables and $C_{ij}^k = \{C_{ij}^1, C_{ij}^2, \dots, C_{ij}^k\}$ is a multi-choice parameter.

The following cases are to be considered

1. Only $s_i, (i = 1, 2, \dots, m)$ follows Weibull distribution.
2. Only $d_j, (j = 1, 2, \dots, n)$ follows Weibull distribution.
3. Both $s_i, (i = 1, 2, \dots, m)$ and $d_j, (j = 1, 2, \dots, n)$ follow Weibull distribution.

2.1. Only $s_i, (i = 1, 2, \dots, m)$ follows Weibull distribution

It is assumed that s_1, s_2, \dots, s_m are independent random variables and $s_i, (i = 1, 2, \dots, m)$ follows Weibull distribution with shape and scale parameters as α_i and β_i respectively, where the aspiration level is $\gamma_i, 0 < \gamma_i < 1$. The constraint (3) can be rewrite as below:

$$\Pr \left(\sum_{j=1}^n x_{ij} \leq s_i \right) \geq 1 - \gamma_i, \quad i = 1, 2, \dots, m.$$

The probability density function of s_i ($i = 1, 2, \dots, m$) is given by

$$f(s_i; \alpha_i, \beta_i) = \frac{\alpha_i}{\beta_i^{\alpha_i}} s_i^{\alpha_i-1} e^{-\left(\frac{s_i}{\beta_i}\right)^{\alpha_i}}$$

$$s_i \geq 0 \text{ and } \alpha_i > 0, \beta_i > 0. \quad (6)$$

Hence the probabilistic constraint can be presented as:

$$\int_{\sum_{j=1}^n x_{ij}}^{\infty} f(s_i; \alpha_i, \beta_i) d(s_i) \geq 1 - \gamma_i. \quad (7)$$

The above integral can be expressed as:

$$\int_{\sum_{j=1}^n x_{ij}}^{\infty} \frac{\alpha_i}{\beta_i^{\alpha_i}} s_i^{\alpha_i-1} e^{-\left(\frac{s_i}{\beta_i}\right)^{\alpha_i}} d(s_i) \geq 1 - \gamma_i. \quad (8)$$

Let, $\left(\frac{s_i}{\beta_i}\right)^{\alpha_i} = z$. The above constraints (8) can be rewrite as:

$$\int_{\left(\frac{\sum_{j=1}^n x_{ij}}{\beta_i}\right)^{\alpha_i}}^{\infty} e^{-z} d(z) \geq 1 - \gamma_i, \quad (9)$$

which can be integrated as:

$$- [e^{-z}]_{\left(\frac{\sum_{j=1}^n x_{ij}}{\beta_i}\right)^{\alpha_i}}^{\infty} \geq 1 - \gamma_i. \quad (10)$$

It can be further simplified as:

$$e^{-\left(\frac{\sum_{j=1}^n x_{ij}}{\beta_i}\right)^{\alpha_i}} \geq 1 - \gamma_i. \quad (11)$$

Taking logarithm in both sides twice,

$$\alpha_i \ln \left(\frac{\sum_{j=1}^n x_{ij}}{\beta_i} \right) \leq \ln \{-\ln(1 - \gamma_i)\}. \quad (12)$$

After simplifying and rearranging the above constraints can be stated as:

$$\ln \left(\sum_{j=1}^n x_{ij} \right) \leq \ln \beta_i + \frac{1}{\alpha_i} \ln \{-\ln(1 - \gamma_i)\}. \quad (13)$$

Thus finally, the probabilistic constraints (3) can be transformed into a deterministic linear constraints as:

$$\sum_{j=1}^n x_{ij} \leq e^{\left[\ln \beta_i + \frac{1}{\alpha_i} \ln \{-\ln(1 - \gamma_i)\} \right]}. \quad (14)$$

Thus, a multi-choice deterministic transportation problem (see **Model 2**) instead of multi-choice stochastic transportation model can be stated as follows.

Model 2:

$$\min : z = \sum_{i=1}^m \sum_{j=1}^n \{C_{ij}^1, C_{ij}^2, \dots, C_{ij}^k\} x_{ij}, \quad k = 1, 2, \dots, K \quad (15)$$

$$\text{subject to } \sum_{j=1}^n x_{ij} \leq e^{\left[\ln \beta_i + \frac{1}{\alpha_i} \ln \{-\ln(1 - \gamma_i)\} \right]} \quad (16)$$

$$\sum_{i=1}^m x_{ij} \geq d_j, \quad j = 1, 2, \dots, n \quad (17)$$

$$x_{ij} \geq 0, \quad \forall i \text{ and } j \quad (18)$$

$$\text{where, } \sum_{i=1}^m e^{\left[\ln \beta_i + \frac{1}{\alpha_i} \ln \{-\ln(1 - \gamma_i)\} \right]} \geq \sum_{j=1}^n d_j$$

(feasibility condition).

2.2. Only $d_j, (j = 1, 2, \dots, n)$ follows Weibull distribution

It is assumed that d_1, d_2, \dots, d_n are independent random variables and $d_j (j = 1, 2, \dots, n)$ follows Weibull distribution with shape and scale parameters as α'_j and β'_j respectively, where the aspiration levels is $\delta_j, 0 < \delta_j < 1$. The constraint of **Model 1** can be written as follows:

$$\Pr \left(\sum_{i=1}^m x_{ij} \geq d_j \right) \geq 1 - \delta_j, \quad j = 1, 2, \dots, n.$$

Rearranging the above constraints can be written as,

$$\Pr \left(\sum_{i=1}^m x_{ij} \leq d_j \right) \leq \delta_j, \quad j = 1, 2, \dots, n. \quad (19)$$

The probability density function of $d_j (j = 1, 2, \dots, n)$ is given by

$$f(d_j; \alpha'_j, \beta'_j) = \frac{\alpha'_j}{\beta'_j \alpha'_j} d_j^{\alpha'_j - 1} e^{-\left(\frac{d_j}{\beta'_j}\right)^{\alpha'_j}} \quad d_j \geq 0 \text{ and } \alpha'_j > 0, \beta'_j > 0. \quad (20)$$

Hence the probabilistic constraint can be presented as:

$$\int_{\sum_{i=1}^m x_{ij}}^{\infty} f(d_j; \alpha'_j, \beta'_j) d(d_j) \leq \delta_j. \quad (21)$$

The above integral can be expressed as:

$$\int_{\sum_{i=1}^m x_{ij}}^{\infty} \frac{\alpha'_j}{\beta'_j \alpha'_j} d_j^{\alpha'_j - 1} e^{-\left(\frac{d_j}{\beta'_j}\right)^{\alpha'_j}} d(d_j) \leq \delta_j \quad (22)$$

Let, $\left(\frac{d_j}{\beta'_j}\right)^{\alpha'_j} = z'$ The above integral (22) can be rewrite as:

$$\int_{\left(\frac{\sum_{i=1}^m x_{ij}}{\beta'_j}\right)^{\alpha'_j}}^{\infty} e^{-z'} d(z') \leq \delta_j, \quad (23)$$

which can be integrated as:

$$- \left[e^{-z'} \right]_{\left(\frac{\sum_{i=1}^m x_{ij}}{\beta'_j}\right)^{\alpha'_j}}^{\infty} \leq \delta_j \quad (24)$$

It can be further simplified as:

$$e^{-\left(\frac{\sum_{i=1}^m x_{ij}}{\beta'_j}\right)^{\alpha'_j}} \leq \delta_j. \quad (25)$$

Taking logarithm in both sides twice,

$$\alpha'_j \ln \left(\frac{\sum_{i=1}^m x_{ij}}{\beta'_j} \right) \geq \ln \{-\ln(\delta_j)\}. \quad (26)$$

After rearranging of the above constraint can be written as:

$$\ln \left(\sum_{i=1}^m x_{ij} \right) \geq \ln \beta'_j + \frac{1}{\alpha'_j} \ln \{-\ln(\delta_j)\}. \quad (27)$$

Thus finally, the probabilistic constraints (4) can be transformed into a deterministic linear constraints as,

$$\sum_{i=1}^m x_{ij} \geq e^{\left[\ln \beta'_j + \frac{1}{\alpha'_j} \ln \{-\ln(\delta_j)\} \right]}. \quad (28)$$

Thus, a multi-choice deterministic transportation problem (see **Model 3**) instead of multi-choice stochastic transportation problem can be expressed as follow.

Model 3:

$$\min : z = \sum_{i=1}^m \sum_{j=1}^n \{C_{ij}^1, C_{ij}^2, \dots, C_{ij}^k\} x_{ij},$$

$$k = 1, 2, \dots, K \quad (29)$$

$$\text{subject to } \sum_{j=1}^n x_{ij} \leq s_i, \quad i = 1, 2, \dots, m \quad (30)$$

$$\sum_{i=1}^m x_{ij} \geq e^{\left[\ln \beta_j' + \frac{1}{\alpha_j'} \ln\{-\ln(\delta_j)\}\right]} \quad (31)$$

$$x_{ij} \geq 0, \quad \forall i \text{ and } j \quad (32)$$

$$\text{where, } \sum_{i=1}^m s_i \geq \sum_{j=1}^n e^{\left[\ln \beta_j' + \frac{1}{\alpha_j'} \ln\{-\ln(\delta_j)\}\right]},$$

(feasibility condition).

2.3. Both s_i , ($i = 1, 2, \dots, m$) and d_j , ($j = 1, 2, \dots, n$) follow Weibull distributions

The shape and scale parameters of the random variables s_i and d_j are known and previously defined. In this case, both s_i and d_j follow Weibull distribution. **Model 1** is transferred into an equivalent deterministic model as:

Model 4:

$$\min : z = \sum_{i=1}^m \sum_{j=1}^n \{C_{ij}^1, C_{ij}^2, \dots, C_{ij}^k\} x_{ij},$$

$$k = 1, 2, \dots, K \quad (33)$$

$$\text{subject to } \sum_{j=1}^n x_{ij} \leq e^{\left[\ln \beta_i + \frac{1}{\alpha_i} \ln\{-\ln(1-\gamma_i)\}\right]} \quad (34)$$

$$\sum_{i=1}^m x_{ij} \geq e^{\left[\ln \beta_j' + \frac{1}{\alpha_j'} \ln\{-\ln(\delta_j)\}\right]} \quad (35)$$

where

$$\sum_{i=1}^m e^{\left[\ln \beta_i + \frac{1}{\alpha_i} \ln\{-\ln(1-\gamma_i)\}\right]} \geq \sum_{j=1}^n e^{\left[\ln \beta_j' + \frac{1}{\alpha_j'} \ln\{-\ln(\delta_j)\}\right]},$$

(feasibility condition).

3. Generalized Transformation of the Objective Function

3.1. Transformation technique: 1

The proposed model is derived for restriction on the upper bound of binary variables on cost coefficients of the objective function:

Case 1:

$$\min : z = \sum_{i=1}^m \sum_{j=1}^n \{C_{ij}^1, C_{ij}^2, \dots, C_{ij}^{n_s}\} x_{ij},$$

$$s = 1, 2, \dots, K$$

The total number of choices for first step is k_s . We proposed that $k_s \geq 2$.

Case 2: The different models also depend upon the set of conjugate terms of binomials coefficients of whose sum is closer or nearer to the aspiration levels or choices.

a. In every different models, the restriction of $(2^{n_s} - k_s)$ indicates the total number of constraints in which firstly there have been auxiliary constraints and in rest of them (constraints) in restriction there also additional constraints.

b. The similar models are also performed in each different models which can depend upon the same restriction, associated with others additional constraints.

Case 3: The number of binary variables for each aspiration levels is required to handle the multi-choice parameters in cost coefficients of the objective function in the following manner.

Find n_s , for which $2^{(n_s-1)} < k_s < 2^{n_s}$, where n_s are represented as the number of binary variables. Let binary variables are $z_{ij}^1, z_{ij}^2, \dots, z_{ij}^{n_s}$; where k_s the number of choices.

Case 4: Expand $2^{n_s} = {}^{n_s}C_0 + {}^{n_s}C_1 + {}^{n_s}C_2 + \dots + {}^{n_s}C_{r_{s1}-1} + {}^{n_s}C_{r_{s1}} + {}^{n_s}C_{r_{s1}+1} + {}^{n_s}C_{r_{s1}+2} + \dots + {}^{n_s}C_{r_{s2}-1} + {}^{n_s}C_{r_{s2}} + {}^{n_s}C_{r_{s2}+1} + {}^{n_s}C_{r_{s2}+2} \dots + {}^{n_s}C_{n_s-1} + {}^{n_s}C_{n_s}$ and select the smallest number of consecutive terms whose sum is "equal to" or "just greater than" k_s from the expression. Let the terms ${}^{n_s}C_{r_{s1}}, {}^{n_s}C_{r_{s1}+1}, {}^{n_s}C_{r_{s1}+2}, \dots, {}^{n_s}C_{r_{s2}-1}, {}^{n_s}C_{r_{s2}}$ are associated to respect the lower and upper bounds.

Case 5: When $2^{n_s} = k_s$, the choices of k_s is equal to the expansion of 2^{n_s} . Then, there does not appear to the introduction of auxiliary and additional constraints involving the binary variables.

Case 6: Assigned k_s binary codes to k_s number of aspiration levels for cost coefficients of the objective function.

$$\begin{aligned} \min : z = & \left[\sum_{i=1}^{n_s C_{r_{s1}}} \sum_{j=1}^{n_s C_{r_{s1}}} A_{ij}^{r_{s1}} B_{ij}^{r_{s1}} C_{ij}^k + \right. \\ & \sum_{i=1}^{n_s C_{r_{s1}+1}} \sum_{j=1}^{n_s C_{r_{s1}+1}} A_{ij}^{r_{s1}+1} B_{ij}^{r_{s1}+1} C_{ij}^{\{n_s C_{r_{s1}}+k\}} +, \\ & \dots, + \sum_{i=1}^{n_s C_{r_{s2}-1}} \sum_{j=1}^{n_s C_{r_{s2}-1}} A_{ij}^{r_{s2}-1} B_{ij}^{r_{s2}-1} \\ & \left. C_{ij}^{\{n_s C_{r_{s1}}+\dots+n_s C_{r_{s2}-2\}+k\}} \right. \\ & \left. + \sum_{i=1}^{(k_s-L_{ij}^1)} \sum_{j=1}^{(k_s-L_{ij}^1)} A_{ij}^{r_{s2}} B_{ij}^{r_{s2}} C_{ij}^{(L_{ij}^1)+k} \right] x_{ij}, \\ & s = 1, 2, \dots, K \end{aligned}$$

where, $L_{ij}^{(1)} = n_s C_{r_{s1}} + n_s C_{r_{s1}+1} + n_s C_{r_{s1}+2} + \dots + n_s C_{r_{s2}-1}$;
 $j'_1 \in \{1, 2, \dots, (n_s - s) + 1\}, j'_2 \in \{2, 3, \dots, (n_s - s) + 2\}, \dots, j'_s \in \{s, s + 1, \dots, n_s\}$;
 $I_s^{(j')} = \{(j'_1, j'_2, \dots, j'_s) / j'_1 < j'_2 < \dots < j'_s, s = r_{s1}, r_{s1}+1, r_{s1}+2, \dots, r_{s2}\}$;
 $A_{ij}^{s_k} = \{z_{ij}^{(j'_1)}, z_{ij}^{(j'_2)}, \dots, z_{ij}^{(j'_s)}\} / \{j'_1, j'_2, \dots, j'_s\} \in I_s^{(j')}$;
 $s = r_{s1}, r_{s1} + 1, r_{s1} + 2, \dots, r_{s2}$.
 Therefore, $B_{ij}^{s_k} = \{\prod_{k=1}^{n_s} (1 - z_{ij}^{j'_k}) / j'_k\}$ not belongs to $\{(j'_1, j'_2, \dots, j'_s)\}$, for all i and j .

Case 7: The number of binary codes is put to the introducing of additional restriction of $(2^{n_s} - k_s)$ having in auxiliary and additional constraints in separately with different models. The auxiliary constraints are also depend open the range of coefficients in each sets of whose sum is nearer to the aspiration levels or choices. But the additional constraints in each models are expressed as the difference between the aspiration level and sum of any about sets of specified binomials coefficients.

$$z_{ij}^1 + z_{ij}^2 + \dots + z_{ij}^{n_s} \geq r_{s1} \tag{36}$$

$$z_{ij}^1 + z_{ij}^2 + \dots + z_{ij}^{n_s} \leq r_{s2} \tag{37}$$

and

$$z_{ij}^{j'_1} + z_{ij}^{j'_2} + \dots + z_{ij}^{j'_{sr2}} \leq r_{s2} - 1 \tag{38}$$

The excess additional constraints should be imposed on $z_{ij}^{j'_1}, z_{ij}^{j'_2}, \dots, z_{ij}^{j'_{sr2}} \in A_{ij}^{sr2k}$ for all i and j .

$$\sum_{t=1}^{n_s} z_{ij}^{(t)} \geq 1, \quad t \in \{j'_1, j'_2, \dots, j'_{rs1}\}$$

Case 8: Formulate the equivalent mathematical model with additional restriction as:

$$\begin{aligned} \min : z = & \left[\sum_{i=1}^{n_s C_{r_{s1}}} \sum_{j=1}^{n_s C_{r_{s1}}} A_{ij}^{r_{s1}} B_{ij}^{r_{s1}} C_{ij}^k + \right. \\ & \sum_{i=1}^{n_s C_{r_{s1}+1}} \sum_{j=1}^{n_s C_{r_{s1}+1}} A_{ij}^{r_{s1}+1} B_{ij}^{r_{s1}+1} C_{ij}^{\{n_s C_{r_{s1}}+k\}} +, \\ & \dots, + \sum_{i=1}^{n_s C_{r_{s2}-1}} \sum_{j=1}^{n_s C_{r_{s2}-1}} A_{ij}^{r_{s2}-1} B_{ij}^{r_{s2}-1} \\ & \left. C_{ij}^{\{n_s C_{r_{s1}}+\dots+n_s C_{r_{s2}-2\}+k\}} \right. \\ & \left. + \sum_{i=1}^{(k_s-L_{ij}^1)} \sum_{j=1}^{(k_s-L_{ij}^1)} A_{ij}^{r_{s2}} B_{ij}^{r_{s2}} C_{ij}^{(L_{ij}^1)+k} \right] x_{ij}, \\ & s = 1, 2, \dots, K \end{aligned}$$

$$z_{ij}^1 + z_{ij}^2 + \dots + z_{ij}^{n_s} \geq r_{s1}$$

$$z_{ij}^1 + z_{ij}^2 + \dots + z_{ij}^{n_s} \leq r_{s2}$$

$$\text{and } z_{ij}^{j'_1} + z_{ij}^{j'_2} + \dots + z_{ij}^{j'_{sr2}} \leq r_{s2} - 1$$

where, $j' = (k_s - L_{ij}^{(1)}) + 1, (k_s - L_{ij}^{(1)}) + 2, \dots, n_s C_{r_{s2}} x_{ij} \geq 0$; for all i and j .
 $z_{ij}^{n_s} = 0/1, n_s = 1, 2, \dots, \{\frac{\ln k_s}{\ln 2}\}$,
 and for all i and j .

Where, $L_{ij}^{(1)} = n_s C_{r_{s1}} + n_s C_{r_{s1}+1} + n_s C_{r_{s1}+2} + \dots + n_s C_{r_{s2}-1}$.

3.2. Transformation technique: 2

The proposed model is derived for restriction on the lower bound of binary variables. The Cases of 1, 2, 3, 4, and 5 are same as the above transformation of 1.

Case 6: Assigned k_s binary codes to k_s number of aspiration levels for cost coefficients of the objective function.

$$\begin{aligned} \min : z = & \left[\sum_{i=1}^{n_s C_{r_{s2}}} \sum_{j=1}^{n_s C_{r_{s2}}} A_{ij}^{r_{s2}} B_{ij}^{r_{s2}} C_{ij}^k + \right. \\ & \sum_{i=1}^{n_s C_{r_{s2}-1}} \sum_{j=1}^{n_s C_{r_{s2}-1}} A_{ij}^{r_{s2}-1} B_{ij}^{r_{s2}-1} C_{ij}^{\{n_s C_{r_{s2}}+k\}} +, \\ & \dots, + \sum_{i=1}^{n_s C_{r_{s1}+1}} \sum_{j=1}^{n_s C_{r_{s1}+1}} A_{ij}^{r_{s1}+1} B_{ij}^{r_{s1}+1} \\ & \left. C_{ij}^{\{n_s C_{r_{s2}}+\dots+n_s C_{r_{s2}+2\}+k\}} \right. \\ & \left. + \sum_{i=1}^{(k_s-L_{ij}^2)} \sum_{j=1}^{(k_s-L_{ij}^2)} A_{ij}^{r_{s1}} B_{ij}^{r_{s1}} C_{ij}^{(L_{ij}^2)+k} \right] x_{ij}, \\ & s = 1, 2, \dots, K \end{aligned}$$

where, $L_{ij}^{(2)} = {}^{n_s}C_{r_{s2}} + {}^{n_s}C_{r_{s2}-1} + {}^{n_s}C_{r_{s2}-2} + \dots + {}^{n_s}C_{r_{s2}+1}$, and $j'_1 \in \{1, 2, \dots, (n_s - s) + 1\}$, $j'_2 \in \{2, 3, \dots, (n_s - s) + 2\}, \dots, j'_s \in \{s, s+1, \dots, n_s\}$;

$I_s^{(j')} = \{(j'_1, j'_2, \dots, j'_s) / j'_1 < j'_2 < \dots < j'_s \mid s = r_{s1}, r_{s1+1}, r_{s1+2}, \dots, r_{s2}\}$

where, $A_{ij}^{s_k} = \{z_{ij}^{(j'_1)}, z_{ij}^{(j'_2)}, \dots, z_{ij}^{(j'_s)} / (j'_1, j'_2, \dots, j'_s) \in I_s^{(j')}\}$, where $s = r_{s1}, r_{s1} + 1, r_{s1} + 2, \dots, r_{s2}$.

Therefore, $B_{ij}^{s_k} = \{\prod_{k=1}^{n_s} (1 - z_{ij}^{j'_k}) / j'_k \mid \text{not belongs to } (j'_1, j'_2, \dots, j'_s)\}$, for all i and j .

Case 7: On restriction of $(2^{n_s} - k_s)$ with the number of binary codes in respect to the additional restriction having auxiliary and additional constraints as follows:

$$z_{ij}^1 + z_{ij}^2 + \dots + z_{ij}^{n_s} \geq r_{s1}, \quad (39)$$

$$\text{and } z_{ij}^1 + z_{ij}^2 + \dots + z_{ij}^{n_s} \leq r_{s2}, \quad (40)$$

for all i and j . The excess additional constraints should be imposed on $z_{ij}^{j'_1}, z_{ij}^{j'_2}, \dots, z_{ij}^{j'_{sr2}} \in A_{ij}^{sr2k}$ for all i and j .

$$\sum_{t=1}^{n_s} z_{ij}^{(t)} \geq 1, \quad t \text{ not belongs to } \{j'_1, j'_2, \dots, j'_{r_{s1}}\}.$$

Case 8: Formulate the equivalent mathematical model with additional restriction as:

$$\begin{aligned} \min : z = & \left[\sum_{i=1}^{n_s C_{r_{s2}}} \sum_{j=1}^{n_s C_{r_{s2}}} A_{ij}^{r_{s2}} B_{ij}^{r_{s2}} C_{ij}^k + \right. \\ & \sum_{i=1}^{n_s C_{r_{s2}-1}} \sum_{j=1}^{n_s C_{r_{s2}-1}} A_{ij}^{r_{s2}-1} B_{ij}^{r_{s2}-1} C_{ij}^{\{n_s C_{r_{s2}}+k\}} + \\ & \dots + \sum_{i=1}^{n_s C_{r_{s1}+1}} \sum_{j=1}^{n_s C_{r_{s1}+1}} A_{ij}^{r_{s1}+1} B_{ij}^{r_{s1}+1} \\ & \left. C_{ij}^{\{n_s C_{r_{s2}}+\dots+n_s C_{r_{s1}+2\}+k\}} \right. \\ & \left. + \sum_{i=1}^{(k_s - L_{ij}^{(2)})} \sum_{j=1}^{(k_s - L_{ij}^{(2)})} A_{ij}^{r_{s1}} B_{ij}^{r_{s1}} C_{ij}^{(L_{ij}^{(2)})+k} \right] x_{ij}, \end{aligned}$$

$$s = 1, 2, \dots, K.$$

$$z_{ij}^1 + z_{ij}^2 + \dots + z_{ij}^{n_s} \geq r_{s1},$$

$$z_{ij}^1 + z_{ij}^2 + \dots + z_{ij}^{n_s} \leq r_{s2},$$

for all i and j , where, $j' = (k_s - L_{ij}^{(2)}) + 1, (k_s - L_{ij}^{(2)}) + 2, \dots, {}^{n_s}C_{r_{s1}}$; $x_{ij} \geq 0$; $z_{ij}^{n_s} = 0/1$, $n_s = 1, 2, \dots, \{\frac{\ln k_s}{\ln 2}\}$; $L_{ij}^{(2)} = {}^{n_s}C_{r_{s2}} + {}^{n_s}C_{r_{s2}-1} +$

$${}^{n_s}C_{r_{s2}-2} + \dots + {}^{n_s}C_{r_{s1}+1}.$$

Remark: Multi-choice stochastic transportation problem can be transformed to an equivalent mathematical programming problem by using one of the above transformation technique, when the transformation technique is also established in any models, then the cases can be stated as:

Case-1: Different types of models also depend upon the different set of auxiliary equation which is raised by the set of conjugate coefficients in which sum is nearer to the aspiration levels as k_s are ${}^{n_s}C_{r_{s1}}, {}^{n_s}C_{r_{s1}+1}, {}^{n_s}C_{r_{s1}+2}, \dots, {}^{n_s}C_{n_s}$.

Case-2: The additional constraints lead to the sum of conjugate terms (which is just nearer to the choices) - k_s (aspiration levels) greater than 0.

Case-3: In case of $k_s = 2^{n_s}$ involving binary variables, then the expression will be $2^{n_s} = {}^{n_s}C_0 + {}^{n_s}C_1 + {}^{n_s}C_2 + \dots + {}^{n_s}C_{n_s}$ restriction will be as

$$z_{ij}^1 + z_{ij}^2 + \dots + z_{ij}^{n_s} \neq 0, \quad (41)$$

and

$$z_{ij}^1 + z_{ij}^2 + \dots + z_{ij}^{n_s} \neq n_s, \quad (42)$$

for all i and j , hence the above two restriction will not effect on the solution procedure of the mathematical model.

Case-4: When $k_s \neq 2^{n_s}$, then from the expression of 2^{n_s} the smallest number of conjugate terms whose sum is equal or just greater than k_s are ${}^{n_s}C_{r_{s1}}, {}^{n_s}C_{r_{s1}+1}, {}^{n_s}C_{r_{s1}+2}, \dots, {}^{n_s}C_{n_s}$, Hence $k_s \leq {}^{n_s}C_{r_{s1}}, {}^{n_s}C_{r_{s1}+1}, {}^{n_s}C_{r_{s1}+2}, \dots, {}^{n_s}C_{n_s}$, $s = 1, 2, \dots, k$. In this case four possibilities may be arises.

4. Case Study

A reputed cold drinks supply company transports the cold drinks from three product center at Dankuni, Howrah, Asanshol to the four destination center at Jhargram, Kharagpur, Trakeshar and Contai. In summer season, the cold drinks has tremendous demand every time at four destination centers. The transportation time cost is an important factor of transportation planning programme. The transportation time cost is related with fluctuation of competency of driver, road condition etc. The manufacturing time at production centers depends upon the availability of current supply and machine condition and skilled mechanical hands etc. Delivery time is

related with transporting system of smooth distribution of product in due time at destination center. Due to fluctuation of above factor, transportation cost time on each route is not fixed. They are appended below in Table- 1:

Table 1. Multi-choice transportation time cost (in Hours) C_{ij}^k : per unit (1 unit= Milage distance) for route x_{ij} .

Sl. No.	Route: x_{ij}	Transportation time cost
1	(1, 1): x_{11}	12 or 13 or 14
2	(1, 2): x_{12}	15 or 16
3	(1, 3): x_{13}	19 or 20 or 21 or 22
4	(1, 4): x_{14}	24 or 25 or 26
5	(2, 1): x_{21}	16 or 18 or ... or 24 or 26
6	(2, 2): x_{22}	17 or 18 or ... or 21 or 22
7	(2, 3): x_{23}	9 or 10 or 11
8	(2, 4): x_{24}	17 or 18
9	(3, 1): x_{31}	18 or 19 or ... or 23 or 24
10	(3, 2): x_{32}	12 or 13 or ... or 18 or 19
11	(3, 3): x_{33}	25 or 26 or 27
12	(3, 4): x_{34}	28 or 29

A multi-choice stochastic transportation problem is presented where the objective function and the constraints are formulated as:

$$\min : z = \sum_{i=1}^3 \sum_{j=1}^4 \{C_{ij}^1, C_{ij}^2, \dots, C_{ij}^k\} x_{ij}, \quad k = 1, 2, \dots, 10 \quad (43)$$

$$\text{subject to } \Pr \left(\sum_{j=1}^4 x_{ij} \leq s_i \right) \geq 1 - \gamma_i, \quad i = 1, 2, 3 \quad (44)$$

$$\Pr \left(\sum_{i=1}^3 x_{ij} \geq d_j \right) \geq 1 - \delta_j, \quad j = 1, 2, 3, 4 \quad (45)$$

where, $x_{ij} \geq 0, i = 1, 2, 3; j = 1, 2, 3, 4$ and

$$0 < \gamma_i < 1, 0 < \delta_j < 1. \quad (46)$$

In the case study, three known parameters s_1, s_2, s_3 of Weibull distribution is consider. The specified probability levels with shape and scale parameters of supplies s_1, s_2, s_3 are given in the Table -2.

Table 2. Value of shape and scale parameters with Specified prob.levels (SPL) of s_i .

Shape parameters	Scale parameters	(SPL)
$\alpha_1 = 3000$	$\beta_1 = 3.6$	$\gamma_1 = 0.01$
$\alpha_2 = 2500$	$\beta_2 = 3.0$	$\gamma_2 = 0.02$
$\alpha_3 = 2000$	$\beta_3 = 2.4$	$\gamma_3 = 0.03$

Further, the specified probability levels and the shape and the scale parameters of demands parameters d_1, d_2, d_3, d_4 which follow Weibull distribution are given in Table -3.

Table 3. Value of shape and scale parameters with Specified prob.levels (SPL) of d_j .

Shape parameters.	Scale parameters	(SPL)
$\alpha'_1 = 1700$	$\beta'_1 = 2.2$	$\delta_1 = 0.04$
$\alpha'_2 = 1500$	$\beta'_2 = 2.0$	$\delta_2 = 0.05$
$\alpha'_3 = 1250$	$\beta'_3 = 1.6$	$\delta_3 = 0.06$
$\alpha'_4 = 1000$	$\beta'_4 = 1.2$	$\delta_4 = 0.07$

Using the data provided in Table 1,2 and 3 the following deterministic multi-choice transportation problem is formulated as:

$$\begin{aligned} \min : z = & \{12, 13, 14\}x_{11} + \{15, 16\}x_{12} \\ & + \{19, 20, 21, 22\}x_{13} + \{24, 25, 26\}x_{14} \\ & + \{16, 18, 20, 22, 24, 26\}x_{21} \\ & + \{17, 18, 19, 20, 21, 22\}x_{22} \\ & + \{9, 10, 11\}x_{23} + \{17, 18\}x_{24} \\ & + \{18, 19, 20, 21, 22, 23, 24\}x_{31} \\ & + \{12, 13, 14, 15, 16, 17, 18, 19\}x_{32} \\ & + \{25, 26, 27\}x_{33} + \{28, 29\}x_{34} \end{aligned} \quad (47)$$

$$\text{subject to } \sum_{j=1}^4 x_{1j} \leq 3829.430743 \quad (48)$$

$$\sum_{j=1}^4 x_{2j} \leq 3404.6222029 \quad (49)$$

$$\sum_{j=1}^4 x_{3j} \leq 3346.480624 \quad (50)$$

$$\sum_{i=1}^3 x_{i1} \geq 2892.168344 \quad (51)$$

$$\sum_{i=1}^3 x_{i2} \geq 2860.129000 \quad (52)$$

$$\sum_{i=1}^3 x_{i3} \geq 2386.056503 \quad (53)$$

$$\sum_{i=1}^3 x_{i4} \geq 2259.265858 \quad (54)$$

$$x_{ij} \geq 0, \quad i = 1, 2, 3 \text{ and } j = 1, 2, 3, 4.$$

Now using a new transformation technique, the following multi-choice deterministic transportation problem is obtained as bellow:

$$\begin{aligned} \min : z &= t_{11}x_{11} + t_{12}x_{12} + t_{13}x_{13} + t_{14}x_{14} \\ &+ t_{21}x_{21} + t_{22}x_{22} + t_{23}x_{23} + t_{24}x_{24} \\ &+ t_{31}x_{31} + t_{32}x_{32} + t_{33}x_{33} + t_{34}x_{34} \end{aligned} \quad (55)$$

subject to (48) – (54)

where

$$t_{11} = 12z_{11}^1 z_{11}^2 + 13z_{11}^1 (1 - z_{11}^2) + 14(1 - z_{11}^1) z_{11}^2 \quad (56)$$

$$t_{12} = 15z_{12}^1 + 16(1 - z_{12}^1) \quad (57)$$

$$t_{13} = 19z_{13}^1 z_{13}^2 + 20z_{13}^1 (1 - z_{13}^2) + 21(1 - z_{13}^1) z_{13}^2 + 22(1 - z_{13}^1) (1 - z_{13}^2) \quad (58)$$

$$t_{14} = 25z_{14}^1 z_{14}^2 + 26z_{14}^1 (1 - z_{14}^2) + 27(1 - z_{14}^1) z_{14}^2 \quad (59)$$

$$\begin{aligned} t_{21} &= 16z_{21}^1 (1 - z_{21}^2) (1 - z_{21}^3) \\ &+ 18(1 - z_{21}^1) z_{21}^2 (1 - z_{21}^3) \\ &+ 20(1 - z_{21}^1) (1 - z_{21}^2) z_{21}^3 \\ &+ 22z_{21}^1 z_{21}^2 (1 - z_{21}^3) \\ &+ 24(1 - z_{21}^1) z_{21}^2 z_{21}^3 + 26z_{21}^1 (1 - z_{21}^2) z_{21}^3 \end{aligned} \quad (60)$$

$$\begin{aligned} t_{22} &= 17z_{22}^1 (1 - z_{22}^2) (1 - z_{22}^3) \\ &+ 18(1 - z_{22}^1) z_{22}^2 (1 - z_{22}^3) + 19z_{22}^1 z_{22}^2 (1 - z_{22}^3) \\ &+ 20(1 - z_{22}^1) (1 - z_{22}^2) z_{22}^3 + 21z_{22}^1 (1 - z_{22}^2) z_{22}^3 \\ &+ 22(1 - z_{22}^1) z_{22}^2 z_{22}^3 \end{aligned} \quad (61)$$

$$t_{23} = 9z_{23}^1 z_{23}^2 + 10z_{23}^1 (1 - z_{23}^2) + 11(1 - z_{23}^1) z_{23}^2 \quad (62)$$

$$t_{24} = 17z_{24}^1 + 18(1 - z_{24}^1) \quad (63)$$

$$\begin{aligned} t_{31} &= 18(1 - z_{31}^1) (1 - z_{31}^2) (1 - z_{31}^3) \\ &+ 19z_{31}^1 (1 - z_{31}^2) (1 - z_{31}^3) \\ &+ 20(1 - z_{31}^1) z_{31}^2 (1 - z_{31}^3) \\ &+ 21(1 - z_{31}^1) (1 - z_{31}^2) z_{31}^3 \\ &+ 22z_{31}^1 z_{31}^2 (1 - z_{31}^3) + 23z_{31}^1 (1 - z_{31}^2) z_{31}^3 \\ &+ 24(1 - z_{31}^1) z_{31}^2 z_{31}^3 \end{aligned} \quad (64)$$

$$\begin{aligned} t_{32} &= 12z_{32}^1 z_{32}^2 z_{32}^3 + 13(1 - z_{32}^1) z_{32}^2 z_{32}^3 \\ &+ 14z_{32}^1 (1 - z_{32}^2) z_{32}^3 \\ &+ 15z_{32}^1 z_{32}^2 (1 - z_{32}^3) + 16(1 - z_{32}^1) (1 - z_{32}^2) z_{32}^3 \\ &+ 17z_{32}^1 (1 - z_{32}^2) (1 - z_{32}^3) \\ &+ 18(1 - z_{32}^1) z_{32}^2 (1 - z_{32}^3) \end{aligned}$$

$$+ 19(1 - z_{32}^1) (1 - z_{32}^2) (1 - z_{32}^3) \quad (65)$$

$$t_{33} = 25z_{33}^1 z_{33}^2 + 26z_{33}^1 (1 - z_{33}^2) + 27(1 - z_{33}^1) z_{33}^2 \quad (66)$$

$$t_{34} = 28z_{34}^1 + 29(1 - z_{34}^1) \quad (67)$$

$$z_{11}^1 + z_{11}^2 \geq 1 \quad (68)$$

$$z_{14}^1 + z_{14}^2 \geq 1 \quad (69)$$

$$1 \leq z_{21}^1 + z_{21}^2 + z_{21}^3 \leq 2 \quad (70)$$

$$1 \leq z_{22}^1 + z_{22}^2 + z_{22}^3 \leq 2 \quad (71)$$

$$z_{23}^1 + z_{23}^2 \geq 1 \quad (72)$$

$$z_{31}^1 + z_{31}^2 + z_{31}^3 \leq 2 \quad (73)$$

$$z_{33}^1 + z_{33}^2 \geq 1 \quad (74)$$

where

$$x_{ij} \geq 0, \quad i = 1, 2, 3 \text{ and } j = 1, 2, 3, 4. \quad (75)$$

The above mathematical programming model is treated as a non-linear mixed integer programming problem, which is solved by using Lingo 11.0 [16] software. The optimal solution is obtained as : $x_{11}=2892.168$, $x_{14}=937.2624$, $x_{23}=2386.057$, $x_{24}=1018.566$, $x_{32}=2860.139$, $x_{34}=303.4378$ where rest of the decision variables are zero. The minimum time cost of the objective function is 138808.44. For the optimal value of the objective function, the multi-choice cost coefficients are obtained as follows:

x_{ij}	x_{11}	x_{12}	x_{13}	x_{14}	x_{21}	x_{22}
	x_{23}	x_{24}	x_{31}	x_{32}	x_{33}	x_{34}
value of C_{ij}^k	12	15	19	24	16	19
	9	17	24	12	27	28

If the decision variables x_{ij} , $i = 1, 2, 3$; $j = 1, 2, 3, 4$ are considered to be integers, the optimal solution can be obtained as : $x_{11}=2893$, $x_{14}=936$, $x_{23}=2387$, $x_{24}=1017$, $x_{32}=2861$, $x_{34}=307$ where rest of the decision variables are zero. The minimum time cost of the objective function is 138880.00. For the optimal value of the objective function, the multi-choice cost coefficients are obtained as follows:

x_{ij}	x_{11}	x_{12}	x_{13}	x_{14}	x_{21}	x_{22}
	x_{23}	x_{24}	x_{31}	x_{32}	x_{33}	x_{34}
value of C_{ij}^k	12	15	19	24	16	18
	9	17	24	12	25	28

5. Conclusion

This paper proposes a solution procedure to multi-choice stochastic unbalanced transportation problem involving multiplicative terms of binary variables in all cost coefficient of the objective function and subject to some probabilistic

linear constraints associated with Weibull distribution. The binary variables for each choices are dependent on relation $\frac{\ln k_i}{\ln(2)}$, where k_i is the number of choices.

Initially, all the stochastic constraints are transformed into equivalent deterministic constraints. In this paper, the generalized multi-choice programming technique has been incorporated, where the multi-choice type cost coefficients are handled by transferring into an equivalent deterministic model. The additional restrictions involving binary variables are used in some cases of the transformed models to restrict the repetition of goals. After introduction the auxiliary and additional constraints in terms of binary variables with multi-choice parameters are transformed into mixed integer programming problem. In this paper, the three models such as **2** and **3** and **4** are also established, and would be obtained the optimal solution in each models. But now the last case (Model-4) is illustrated with a numerical example. A further study is needed for the models with multi-choice parameters in coefficients of variables in source and destination constraints, and cost coefficients also follow the randomness depending on the problems.

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