

RESEARCH ARTICLE

### The effect of a psychological scare on the dynamics of the tumor-immune interaction with optimal control strategy

Rafel Ibrahim Salih<sup>*a*</sup>, Shireen Jawad<sup>*a*\*</sup>, Kaushik Dehingia<sup>*b*</sup>, Anusmita Das<sup>*c*</sup>

<sup>a</sup> Department of Mathematics, College of Science, University of Baghdad, Baghdad, Iraq

<sup>b</sup>Department of Mathematics, Sonari College, Sonari 785690, Assam, India

<sup>c</sup>Department of Mathematics, Udalguri College, Udalguri 784509, Assam, India

rafel.rabiaa90@gmail.com, Shireen.jawad@sc.uobaghdad.edu.iq, kaushikdehingia17@gmail.com,

anusmitadas 87@gmail.com

#### ARTICLE INFO

Article History: Received 4 January 2024 Accepted 12 March 2024 Available Online 24 July 2024

Keywords: Immune system Local stability Global stability Bifurcation analysis Numerical simulation

AMS Classification 2010: 34D20; 37G10; 65L06; 92C50

#### ABSTRACT

Contracting cancer typically induces a state of terror among the individuals who are affected. Exploring how chemotherapy and anxiety work together to affect the speed at which cancer cells multiply and the immune system's response model is necessary to come up with ways to stop the spread of cancer. This paper proposes a mathematical model to investigate the impact of psychological scare and chemotherapy on the interaction of cancer and immunity. The proposed model is accurately described. The focus of the model's dynamic analysis is to identify the potential equilibrium locations. According to the analysis, it is possible to establish three equilibrium positions. The stability analysis reveals that all equilibrium points consistently exhibit stability under the defined conditions. The bifurcations occurring at the equilibrium sites are derived. Specifically, we obtained transcritical, pitchfork, and saddle-node bifurcation. Numerical simulations are employed to validate the theoretical study and ascertain the minimum therapy dosage necessary for eradicating cancer in the presence of psychological distress, thereby mitigating harm to patients. Fear could be a significant contributor to the spread of tumors and weakness of immune functionality.

(cc) BY

### 1. Introduction

Models are instruments utilized in medicine and science to interpret results, develop hypotheses, and plan experiments to verify them [1]. For instance, mathematical models of population dynamics are frequently represented by differences or differential equations that characterize the temporal evolution of populations [2–9]. Throughout history, ecology predominantly employed mathematical has models to offer qualitative explanations for natural patterns. An exemplary illustration of this methodology was the endeavour to elucidate species diversity through competition models [10–16]. Mathematicsematical modeling is a highly versatile instrument in the field of infectious disease epidemiology, enabling the detection of epidemic patterns, extrapolation of epidemic behaviors, and evaluation of the impact of interventions, including pharmacological treatment, immunization, quarantine, social distance, and hygiene practices, among others [17–22]. An example of a disease model is cancer, which is characterized by the proliferation of malignant cells that infiltrate other anatomical structures and currently ranks as the second most prevalent cause of mortality globally, surpassed only by cardiovascular disease. Developing novel treatment options is a burgeoning study field for scientists seeking to manage cancer effectively. Nevertheless, comprehending the

<sup>\*</sup>Corresponding Author

intricacies of tumor cell proliferation and their intricate interplay with the immune system is crucial in order to devise novel therapeutic To accomplish this, researchers approaches. extensively depended on mathematical models Several scientists have extensively [23-27].researched the mathematical modeling of tumor evolution, its interaction with different cells, and the process of tumor growth. They have achieved this by creating multiple models over the past few decades [28–33]. Cancer is amenable to a variety of treatment modalities, including chemotherapy, radiotherapy, and surgery. Chemotherapy, one of the cancer treatments, is a systematic approach that targets and eliminates cancer cells at the site of the tumor while minimizing its impact on effector-normal cells. This eliminates the ability of the tumor cells to metastasize to other anatomical sites [34-36]. For instance, De Pillis and his associates examined multiple mathematical models to quantify the effects of chemotherapy [37]. In addition, Pillis et al. devised a cancer treatment model in which they discovered that combining chemotherapy and immunotherapy can completely eradicate the tumor instead of using either therapy alone [38]. On the other hand, The initial mathematical model that incorporated the influence of fear in a predator-prey system involving two species was presented by Wang et al. in 2016 [39]. Prey animals may alter their grazing location to a more secure area and relinquish their most productive feeding sites due to predator-induced anxiety. The user's text is incomplete and lacks information [40–43]. Further, There has been a recent increase in research focusing on the importance of mathematical models for studying how fear-induced behavioral changes impact the spread of diseases [44–48]. A medical has demonstrated that psychological study stress contributes to the dissemination of cancer cells throughout the patient's body. Psychological stress causes significant dilation and intensification of blood vessels, hence promoting the migration of cancer cells and facilitating the metastasis of the disease [49]. Researchers have discovered that stress-induced hormones exacerbate the proliferation of cancer cells inside the "lymphatic system," thus facilitating their dissemination to other locations, thereby promoting the metastasis of the disease throughout the human body [50].

The present study proposes a psychological scare-cancer-immune-normal-chemotherapy model (PSCINC) regulated by systems of ordinary differential equations, drawing inspiration from the model presented in [51]. We have enhanced the model of De Pillis et al. by replacing the linear functional response with the Holling type II functional response. This modification allows us to accurately depict the eradication of tumor cells by the immune system, considering the possibility of a weakened immune system due to the presence of psychological scare of cancer. Further, there is a lack of study about the influence of fear on the immune-cancer model. Hence, we deem it imperative to examine this phenomenon, as it contributes to reducing the occurrence of catastrophic circumstances.

Further, there is a lack of study about the influence of fear on the immune-cancer model. Hence, we deem it imperative to examine this phenomenon, as it contributes to reducing the occurrence of catastrophic circumstances. Therefore, this study is dedicated to discussing the impact of anxiety on immune cancer patients, which could be a significant contributor to the spread of tumors and weakness of immune functionality. The subsequent sections of this document are organized as follows: section 2 examines the assumptions of the proposed model. The presence of potential equilibrium points is determined in section 3. Next, section 4 discusses the stability conditions of the steady states. The discussion in section 5 focuses on the global stability of equilibriums. In addition, section 6 acknowledges the local bifurcation conditions in close proximity to the fixed points. In section 7, numerical examinations are conducted to validate our analytical findings.

### 2. Assumptions of the model

Let's examine a system of differential equations (PSCINC) that involves immune cells I (t), tumor cells C(t), normal cells N(t), and chemotherapy treatment H(t) represented as

$$\frac{dI}{dt} = \frac{\alpha}{1+eC} + \frac{p_1 IC}{\beta_1 + C} - p_2 IC - d_1 I - d_2 IH 
= h_1(I, C, H) 
\frac{dC}{dt} = m_1 C (1 - k_1 C) - \frac{p_3 IC}{\beta_2 + C} - \gamma_1 CN - d_3 HC 
= h_2(I, C, N, H) 
\frac{dN}{dt} = m_2 N (1 - k_2 N) - \gamma_2 CN = h_3(C, N) 
\frac{dH}{dt} = \nu - d_4 H = h_4(H)$$
(1)

In the first equation of the PSCINC model, the term  $\frac{\alpha}{1+eC}$  stands for the regular production of immune cells in the body, which is affected by

the presence of cancer cells by the psychological scare factor e. Therefore, e the birth-term changes by producing fear function. The fear function is incorporated by the decreasing function  $\varphi(e, C) = \frac{1}{1+eC}$ , which was initially introduced by Wang et al. [46]. From the biological point of view,  $\varphi(e, C)$  is appropriate since

$$\begin{split} \phi(0,C) &= 1, \phi(e,0) = 1, \\ \lim_{e \to \infty} \phi(e,C) &= 0, \\ \lim_{C \to \infty} \phi(e,C) &= 0, \\ \frac{\partial \phi(e,C)}{\partial e} < 0, \frac{\partial \phi(e,C)}{\partial C} < 0. \end{split}$$

The Michaelis–Menten term  $\frac{p_1 \ IC}{\beta_1+C}$  signifies the existence of tumor cells that provoke the immune system's response.  $p_2 IC$  indicates the immune cells' decay rate due to tumor cells.  $d_1 I$  denotes the effector cells' death rate.  $d_2 I H$  designates the decay rate of effector cells due to chemo-drug. In the second equation, the  $(m_1 C (1 - k_1 C))$  represents the tumor growth term. The term  $\frac{p_3 IC}{\beta_2+C}$  stands for the eradication

of cancerous cells by the body's immune system.  $\gamma_1 CN$  indicates the tumor cells' decay rate due to effector cells.  $d_3HC$  designates the decay rate of cancer cells due to chemo-drug. In the third equation,  $m_2N(1-k_2N)$  denotes the normal cells' growth.  $\gamma_2 CN$  represents the rate of disintegration of normal cells caused by the presence of tumor cells. In the last equation,  $\nu$ is the infusion of chemotherapy drugs externally, and  $d_4H$  is the decay rate of the chemo-drug. All parameters were considered non-negative and visibly described in Table 1. Further, Figure 1 illustrates the schematic sketch of the (PSCINC) model.

The subsequent theorem establishes the positivity of all solutions of the (PSCINC) model in the positive orthant of  $R_{+}^{4}$ .

Theorem **1.** All ofthesolutionsof (PSCINC) modelI(t), C(t), N(t)theand H(t)with theinitial conditions  $(I(0), C(0), N(0), H(0)) \in \mathbb{R}^4_+$ arepositively invariant.



(b) After treatment

Figure 1. Schematic diagram of the (PSCINC) model.

Parameters	Denotation	Values	Source
α	A constant rate of immune cells	0.05	[47]
e	Psychological scare rate from cancer	0.1	Estimated
$p_1$	Maximum immune cell recruitment by tumor cells	0.1	[53]
$\beta_1$	Half-life of effector cells	0.4	[53]
$p_2$	Efficient elimination rate of malignant cells from effector cells	0.2	[47]
$d_1$	Effector cells' death rate	0.2	[53]
$d_2$	Decay rate of effector cells due to chemo-drug	0.09	$\begin{bmatrix} 53 \end{bmatrix}$
$m_1$	Tumor's intrinsic growth rate	0.4	53
$k_1$	Tumor cells' carrying capacity	1.5	$\begin{bmatrix} 53 \end{bmatrix}$
$p_3$	Maximum rate of killing the tumor cells by effector cells	0.3	[47]
$\beta_2$	Half-life of cancer cells.	0.4	[53]
$\gamma_1$	Tumor cell decay rate due to normal cells	0.2	$\begin{bmatrix} 53 \end{bmatrix}$
$d_3$	Decay rate of cancer cells due to chemo-drug	0.05	[53]
$m_2$	Normal cell's intrinsic growth rate	0.35	[53]
$k_2$	Normal cells' carrying capacity	1	$\begin{bmatrix} 53 \end{bmatrix}$
$\gamma_2$	Normal cell decay rate due to tumor cells	0.25	[53]
u	Infusion rate of chemotherapy drugs	0.019	53
$d_4$	Decay rate of the chemo-drug	0.05	[53]

Table 1. Description of (PSCINC) system's parameters.

**Proof.** By integrating the second and third functions of the (PSCINC) model for C(t) and N(t) with a positive initial condition (I(0), C(0), N(0), H(0)), we obtain C(t) =

$$C(0) \exp\left\{\int_{0}^{t} \left[m_{1} - m_{1}k_{1}C(s) - \frac{p_{3}I(s)}{\beta_{2} + C(s)} - \gamma_{1}N(s) - d_{3}H(s)\right]ds\right\} = Q_{C} > 0$$
$$N(t) = N(0) \exp\left\{\int_{0}^{t} \left[m_{2} - m_{2}k_{2}N(s) - \gamma_{2}C(s)\right]ds\right\} = Q_{N} > 0$$

From the first equation of the (PSCINC) model, we have

$$dI = \left(\frac{\alpha}{1+eC} + \frac{p_1 IC}{\beta_1 + C} - p_2 IC - d_1 I - d_2 IH\right) d$$
$$dI \ge \left[\frac{\alpha}{1+eQ_C} + I\left(\frac{p_1 Q_C}{\beta_1 + Q_C} - p_2 Q_C - d_1\right) - \frac{d_2 \nu}{d_4}\right] dt$$

Therefore, after eliminating the non-negative terms, this produces 0000-0003-4022-8053

$$dI \ge \left[ I \left( \frac{p_1 Q_C}{\beta_1 + Q_C} - p_2 Q_C - d_1 - \frac{d_2 \nu}{d_4} \right) \right] dt$$

Consequently, by integrating the equation shown above for I(t), these yields

$$I(t) \ge I(0) \exp\left\{\int_{0}^{t} \left[ \left(\frac{p_{1}Q_{C}}{\beta_{1} + Q_{C}} - p_{2}Q_{C} - d_{1} - \frac{d_{2}\nu}{d_{4}}\right) \right] ds \right\}$$

Similarly, from the last equation of the (PSCINC) model, we get

$$dH = (\nu - d_4 H) \, dt \Longrightarrow dH \ge -d_4 H dt$$

By integrating the above equation, we get

$$H(t) \ge H(0) \exp\left\{\int_0^t -d_4 ds\right\}$$

Thus, H(t) > 0 as  $t \to \infty$ .

As a result of the exponential function's definition, any solution (I(t), C(t), N(t), H(t))that starts inside of  $R^4_+$  with positive initial conditions (I(0), C(0), N(0), H(0)) will remain in  $R^4_+$ .

**Theorem 2.** All the solutions of the (PSCINC) model are uniformly bounded if the following condition is hold

**Proof.** let  $(I(0), C(0), N(0), H(0)) \in \mathbb{R}^4_+$  be an initial condition for the (PSCINC), then, by using the Bernoulli method, we get

$$\frac{dN}{dt} = m_2 N \left(1 - k_2 N\right) - \gamma_2 C N \le m_2 N \left(1 - k_2 N\right)$$
$$\implies N\left(t\right) \le \frac{1}{k_2 + N\left(0\right) e^{-m_2 t}}$$

Thus,  $\lim_{t\to\infty} \sup [N(t)] \leq \frac{1}{k_2}$ . Similarly, we get

$$\lim_{t \to \infty} \sup\left[C\left(t\right)\right] \le \frac{1}{k_1},$$

Now, by using the standard comparison theory [48] and the above bound for the cancer cells, we get

$$\frac{dI}{dt} = \frac{\alpha}{1 + eC} + \frac{p_1 IC}{\beta_1 + C} - p_2 IC - d_1 I - d_2 IH$$
$$\leq \alpha - d_1 I \Longrightarrow \lim_{t \to \infty} \sup \left[ I\left(t\right) \right] \leq \frac{\alpha}{d_1}$$

and

$$\lim_{t \to \infty} \sup \left[ H\left(t\right) \right] \le \frac{\nu}{d_4}$$

Therefore, the corresponding domain region for the (PSCINC) model is

$$\varphi = \left\{ (I, C, N, H) \in R_+^4 : I(t) \le \frac{\alpha}{d_1}, \\ C(t) \le \frac{1}{k_1}, N(t) \le \frac{1}{k_2}, H(t) \le \frac{\nu}{d_4} \right\}.$$

### 3. Equilibria analysis

This section will delve into finding the possible equilibrium and analyzing the system's stability, specifically its stability in the vicinity of equilibrium. To accomplish this, we compute  $\frac{dI}{dt} = \frac{dC}{dt} = \frac{dN}{dt} = \frac{dH}{dt} = 0$  and get the following equilibrium in two cases:

- (1) No treatment case: in this case, we have two equilibrium points given by
  - (a) The cancer-free or healthy point  $A_0 = (I_0, 0, N_0)$ , where  $I_0 = \frac{\alpha}{d_1}$  and  $N_0 = \frac{1}{k^2}$ .
  - (b) The endemic or treatment-free equilibrium point  $A_1 = (I_1, C_1, N_1)$ here  $N_1 = \frac{m_2 - \gamma_2 C_1}{m_2 k_2}, I_1 = \frac{-\alpha(\beta_1 + C_1)}{r_1 C_1 + r_2 C_1^2 - r_3 C_1^3 - r_4}$  where

$$\begin{aligned} r_1 &= p_1 - p_2 \beta_1 - d_1 - e d_1 \beta_1, \\ r_2 &= e p_1 - p_2 - e \beta_1 p_2 - e d_1, \\ r_3 &= e p_2, \\ r_4 &= d_1 \beta_1, \\ r_5 &= m_1 k_1 - \frac{\gamma_1 \gamma_2}{m_2 k_2}, \\ r_6 &= m_1 - \frac{\gamma_1}{k_2}, \end{aligned}$$

and  $C_1$  is the root of the following equation

$$f_1(C) = a_1 C^5 + a_2 C^4 + a_3 C^3 + a_4 C^2 + a_5 C + a_6, = 0,$$
  
where,

$$\begin{aligned} a_1 &= r_3 r_5, \\ a_2 &= (r_5 (\beta_2 r_3 - r_2) - r_3 r_6) \\ a_3 &= - (r_5 (r_1 + r_2 \beta_2) + r_6 (\beta_2 r_3 - r_2)) \,. \\ a_4 &= (r_5 (r_4 + r_1 \beta_2) + r_6 (r_1 + \beta_2 r_2)) \,. \\ a_5 &= (\alpha p_3 - r_6 (r_4 + r_1 \beta_2) + \beta_2 r_4 r_5) \,. \\ a_6 &= (\alpha \beta_1 p_3 - \beta_2 r_4 r_6) \,. \\ &\qquad \text{Clearly, } f_1 (0) = (\alpha \beta_1 p_3 - \beta_2 r_4 r_6), \text{ and} \end{aligned}$$

$$f_{1}(k_{1}) = r_{3}r_{5}k_{1}^{5} + (r_{5}(\beta_{2}r_{3} - r_{2}) - r_{3}r_{6})k_{1}^{4}$$
  
-  $(r_{5}(r_{1} + r_{2}\beta_{2}) + r_{6}(\beta_{2}r_{3} - r_{2}))k_{1}^{3}$   
+  $(r_{5}(r_{4} - r_{1}\beta_{2}) + r_{6}(r_{1} + \beta_{2}r_{2}))k_{1}^{2}$   
+  $(\alpha p_{3} - r_{6}(r_{4} - r_{1}\beta_{2}) + \beta_{2}r_{4}r_{5})k_{1}$   
+  $\alpha\beta_{1}p_{3} - \beta_{2}r_{4}r_{6}.$ 

Therefore, by the intermediate value theorem [55],  $f_1(C)$  has a positive root, say  $C_1$  in the interval  $(0, k_1)$  if one of the following conditions is satisfied

$$f_1(0) < 0 \text{ and } f_1(k_1) > 0,$$
  
 $f_1(0) > 0 \text{ and } f_1(k_1) < 0.$ 

Now, for  $I_1$  and  $N_1$  to be positive, the following two conditions must be satisfied:

$$m_2 > \gamma_2 C_1 r_1 C_1 + r_2 C_1^2 < r_3 C_1^3 + r_4$$
(2)

(2) After treatment case: in this case, we have one positive equilibrium point  $A_2 = (I_2, C_2, N_2, H_2)$  here

$$H_2 = \frac{\nu}{d_4}, N_2 = \frac{m_2 - \gamma_2 C_2}{m_2 k_2}, I_2$$
$$= \frac{-\alpha(\beta_1 + C_2)}{-z_0 C_2^3 - z_1 C_2^2 + z_2 C_2 - z_3}$$
where

$$\begin{aligned} z_0 &= ep_2, z_1 = p_2 - ep_1 + e\beta_1 p_2 + ed_1 + \frac{e\nu d_2}{d_4}, \\ z_2 &= p_1 - p_2\beta_1 - d_1 - ed_1\beta_1 - \frac{\nu d_2}{d_4} - \frac{e\nu d_2\beta_1}{d_4}, \\ z_3 &= d_1\beta_1 + \frac{\nu d_2\beta_1}{d_4}, \end{aligned}$$

The effect of a psychological scare on the dynamics of the tumor-immune interaction ....

$$z_4 = m_1 k_1 - \frac{\gamma_1 \gamma_2}{m_2 k_2},$$
  
$$z_5 = \frac{\gamma_1}{k_2} - m_1 + \frac{\nu d_3}{d_4},$$

and  $C_2$  is the root of the following equation

$$f_2(C) = b_1 C^5 + b_2 C^4 + b_3 C^3 + b_4 C^2 + b_5 C + b_6 = 0,$$

where

$$b_1 = z_0 z_4,$$
  

$$b_2 = (z_4 (z_1 + z_0 \beta_2) + z_0 z_5).$$
  

$$b_3 = (z_4 (z_1 \beta_2 - z_2) + z_5 (z_1 + z_0 \beta_2)).$$
  

$$b_4 = (z_4 (z_3 - \beta_2 z_2) + z_5 (z_1 \beta_2 - z_2)).$$
  

$$b_5 = (\beta_2 z_3 z_4 + z_5 (z_3 - \beta_2 z_2) + \alpha p_3).$$
  

$$b_6 = \beta_2 z_3 z_5 + \alpha \beta_1 p_3.$$

Clearly,

$$f_2\left(0\right) = \beta_2 z_3 z_5 + \alpha p_3 \beta_1$$

and

$$\begin{split} f_{2}\left(k_{1}\right) &= z_{0}z_{4}k_{1}^{5} \\ &+ \left(z_{4}\left(z_{1}+z_{0}\beta_{2}\right)+z_{0}z_{5}\right)k_{1}^{4} \\ &+ \left(z_{4}\left(z_{1}\beta_{2}-z_{2}\right)+z_{5}\left(z_{1}+z_{0}\beta_{2}\right)\right)k_{1}^{3} \\ &+ \left(z_{4}\left(z_{3}-\beta_{2}z_{2}\right)+z_{5}\left(z_{1}\beta_{2}-z_{2}\right)\right)k_{1}^{2} \\ &+ \left(\beta_{2}z_{3}z_{4}+z_{5}\left(z_{3}-\beta_{2}z_{2}\right)+\alpha p_{3}\right)k_{1} \\ &+ \beta_{2}z_{3}z_{5}+\alpha \beta_{1}p_{3}. \end{split}$$

Therefore, by the intermediate value theorem,  $f_2(C)$  has a positive root, say  $C_2$  in the interval  $(0, k_1)$  if one of the following conditions is satisfied

$$\begin{array}{rl} f_{2}\left(0\right) &< \ 0 \ and \ f_{2}\left(k_{1}\right) > 0, \\ f_{2}\left(0\right) &> \ 0 \ and \ f_{2}\left(k_{1}\right) < 0. \end{array}$$

For  $I_2$  and  $N_2$  to be positive, the following two conditions must be satisfied:

$$m_2 > \gamma_2 C_2 z_2 C_2 < z_0 C_2^3 + z_1 C_2^2 + z_3$$
(3)

Since N = 0 indicates that the patients are deceased, we exclude cases where N = 0 from consideration. In order to analyze the linear stability of the system at the three equilibrium points mentioned above, it is necessary to calculate the Jacobian matrix of the system, and the Jacobian is

$$J = \begin{bmatrix} j_{11} & j_{12} & 0 & j_{14} \\ j_{21} & j_{22} & j_{23} & j_{24} \\ 0 & j_{32} & j_{33} & 0 \\ 0 & 0 & 0 & j_{44} \end{bmatrix}$$
(4)

here.

$$j_{11} = \frac{p_1 C}{\beta_1 + C} - p_2 C - d_1 - d_2 H,$$

$$j_{12} = \frac{-e\alpha}{(1+eC)^2} + \frac{p_1\beta_1I}{(\beta_1+C)^2} - p_2I,$$
  

$$j_{14} = -d_2I,$$
  

$$j_{21} = \frac{-p_3C}{\beta_2+C},$$
  

$$j_{22} = m_1(1-2k_1C) - \frac{p_3\beta_2I}{(\beta_2+C)^2} - \gamma_1N - d_3H,$$
  

$$j_{23} = -\gamma_1C, j_{24} = d_3C,$$
  

$$j_{32} = -\gamma_2N, j_{33} = m_2 - 2m_2k_2N - \gamma_2C,$$
  

$$j_{44} = -d_4.$$

0 1

• The Jacobian matrix at  $A_0 = (I_0, 0, N_0)$  is given as:

$$J(A_0) = \begin{bmatrix} -d_1 & -e\alpha - \frac{p_1\alpha}{\beta_1 d_1} - \frac{p_2\alpha}{d_1} & 0\\ 0 & m_1 - \frac{p_3\alpha}{\beta_2 d_1} - \frac{\gamma_1}{k_2} & 0\\ 0 & -\frac{\gamma_2}{k_2} & -m_2 \end{bmatrix}$$
(5)

Then, the eigenvalues of  $J(A_0)$  are  $\lambda_1^0 = -d_1 < 0, \ \lambda_2^0 = m_1 - \frac{p_3\alpha}{\beta_2 d_1} - \frac{\gamma_1}{k_2}$ and  $\lambda_3^0 < 0$ . Therefore,  $A_0$  is asymptotic stable whenever if

$$m_1 < \frac{p_3\alpha}{\beta_2 d_1} + \frac{\gamma_1}{k_2}$$

• The Jacobian matrix at  $A_1 = (I_1, C_1, N_1)$  is given as:

$$J(A_1) = \begin{pmatrix} a_{11}^{[1]} & a_{12}^{[1]} & 0\\ a_{21}^{[1]} & a_{22}^{[1]} & a_{23}^{[1]}\\ 0 & a_{32}^{[1]} & a_{33}^{[1]} \end{pmatrix}$$
(6)

where

$$\begin{split} a_{11}^{[1]} &= \frac{p_1 C_1}{\beta_1 + C_1} - p_2 C_1 - d_1, \\ a_{12}^{[1]} &= \frac{-e\alpha}{(1 + eC_1)^2} + \frac{p_1 \beta_1 I_1}{(\beta_1 + C_1)^2} - p_2 I_1, \\ a_{21}^{[1]} &= \frac{-p_3 C_1}{\beta_2 + C_1}, \\ a_{22}^{[1]} &= m_1 - 2m_1 k_1 C_1 - \frac{p_3 \beta_2 I_1}{(\beta_2 + C_1)^2} - \gamma_1 N_1, \end{split}$$

$$a_{23}^{[1]} = -\gamma_1 C_1,$$
  

$$a_{32}^{[1]} = -\gamma_2 N_1,$$
  

$$a_{33}^{[1]} = m_2 - 2m_2 k_2 N_1 - \gamma_2 C_1.$$

So, the eigenvalues of  $J(A_2)$  are the roots of the following equation

$$\left(\lambda^3 + U_1\lambda^2 + U_2\lambda + U_3\right) = 0 \tag{7}$$

where:  

$$U_{1} = -\left(a_{11}^{[1]} + a_{22}^{[1]} + a_{33}^{[1]}\right)$$

$$U_{2} = -\left(-a_{11}^{[1]}\left(a_{22}^{[1]} + a_{33}^{[1]}\right) - a_{22}^{[1]}a_{33}^{[1]} + a_{12}^{[1]}a_{21}^{[1]}\right)$$

$$U_{3} = \left(a_{11}^{[1]}\left(a_{23}^{[1]}a_{32}^{[1]} - a_{22}^{[1]}a_{33}^{[1]}\right) + a_{12}^{[1]}a_{21}^{[1]}a_{33}^{[1]}\right)$$

$$U_{1}U_{2} - U_{3} = \left(\left(a_{11}^{[1]} + a_{22}^{[1]} + a_{33}^{[1]}\right) - a_{11}^{[1]}\right)\left(-a_{11}^{[1]} + a_{22}^{[1]}a_{33}^{[1]} + a_{12}^{[1]}a_{32}^{[1]} + a_{12}^{[1]}a_{21}^{[1]}\right)\right)$$

$$- \left(a_{11}^{[1]}\left(a_{23}^{[1]}a_{32}^{[1]} - a_{22}^{[1]}a_{33}^{[1]}\right) + a_{12}^{[1]}a_{21}^{[1]}a_{33}^{[1]}\right)$$

Thus, according to the Routh-Hurwitz rule [56],  $A_1$  will be asymptotically stable if  $U_1 > 0, U_3 > 0$  and  $U_1U_2 > U_3$ .

• The Jacobian matrix at  $A_2 = (I_2, C_2, N_2, H_2)$  is given as:

$$J(A_2) = \begin{bmatrix} a_{11}^{[2]} & a_{12}^{[2]} & 0 & a_{14}^{[2]} \\ a_{21}^{[2]} & a_{22}^{[2]} & a_{23}^{[2]} & a_{24}^{[2]} \\ 0 & a_{32}^{[2]} & a_{33}^{[2]} & 0 \\ 0 & 0 & 0 & a_{44}^{[2]} \end{bmatrix}$$
(8)

where,

$$\begin{aligned} a_{11}^{[2]} &= \frac{p_1 C_2}{\beta_1 + C_2} - p_2 C_2 - d_1 - d_2 H_2, \\ a_{12}^{[2]} &= \frac{-e\alpha}{(1 + eC_2)^2} + \frac{p_1 \beta_1 I_2}{(\beta_1 + C_2)^2} \\ &- p_2 I_2, a_{14}^{[2]} = -d_2 I_2, \\ a_{21}^{[2]} &= \frac{-p_3 C_2}{\beta_2 + C_2}, \\ a_{22}^{[2]} &= m_1 - 2m_1 k_1 C_2 - \frac{p_3 \beta_2 I_2}{(\beta_2 + C_2)^2} \\ &- \gamma_1 N_2 - d_3 H_2, \\ a_{23}^{[2]} &= -\gamma_1 C_2, a_{24}^{[2]} = -d_3 C_2, \\ a_{32}^{[2]} &= -\gamma_2 N_2, \\ a_{33}^{[2]} &= m_2 - 2m_2 k_2 N_2 - \gamma_2 C_2, \\ a_{44}^{[2]} &= -d_4. \end{aligned}$$

So, the eigenvalues of  $J(A_2)$  are the roots of the following equation

$$(-d_4 - \lambda)\left(\lambda^3 + D_1\lambda^2 + D_2\lambda + D_3\right) = 0 \quad (9)$$

$$\begin{split} D_1 &= -\left(a_{11}^{[2]} + a_{22}^{[2]} + a_{33}^{[2]}\right) \\ D_2 &= -\left(-a_{11}^{[2]} \left(a_{22}^{[2]} + a_{33}^{[2]}\right) \\ &- a_{22}^{[2]}a_{33}^{[2]} + a_{23}^{[2]}a_{32}^{[2]} + a_{12}^{[2]}a_{21}^{[2]}\right) \\ D_3 &= \left(a_{11}^{[2]} \left(a_{23}^{[2]}a_{32}^{[2]} - a_{22}^{[2]}a_{33}^{[2]}\right) + a_{12}^{[2]}a_{21}^{[2]}a_{33}^{[2]}\right) \\ D_1 D_2 - D_3 &= \left(\left(a_{11}^{[2]} + a_{22}^{[2]} + a_{33}^{[2]}\right) \\ \left(-a_{11}^{[2]} \left(a_{22}^{[2]} + a_{33}^{[2]}\right) - a_{22}^{[2]}a_{33}^{[2]} \\ &+ a_{23}^{[2]}a_{32}^{[2]} + a_{12}^{[2]}a_{21}^{[2]}\right) \right) \\ - \left(a_{11}^{[2]} \left(a_{23}^{[2]}a_{32}^{[2]} - a_{22}^{[2]}a_{33}^{[2]}\right) + a_{12}^{[2]}a_{21}^{[2]}a_{33}^{[2]}\right). \end{split}$$

Thus, according to the Routh-Hurwitz rule,  $A_2$  will be asymptotically stable on the condition that  $D_1 > 0, D_3 > 0$  and  $D_1D_2 > D_3$ .

# 4. Global stability at the cancer-free steady state

To reach a healthy state, in this section, we will examine the global stability surrounding  $A_0$  to explore the dynamics of the (PSCINC) system at regions far from the equilibrium point  $A_0$ .

**Theorem 3.**  $A_0$  is a GAS provided the following conditions hold:

$$m_{1}k_{1} \geq max \left\{ \frac{2}{d_{1}} \left( \frac{-\alpha e}{1+eC} + \frac{p_{1}I}{\beta_{1}+C} - p_{2}I \right)^{2}, \frac{2\gamma_{2}^{2}}{m_{2}k_{2}} \right\}$$

$$m_{1} < \frac{p_{3}I}{\beta_{2}+C} + \gamma_{1}N$$
(10)

**Proof.** Let's define a Lyapunov function [57] for the (PSCINC) model at  $A_0$  as follows:  $L(t) = \frac{(I-I_0)^2}{2} + C + \left(N - N_0 - N_0 ln \frac{N}{N_0}\right)$ , where L(t) is a positive definite about  $A_0$ . Thus,

$$\begin{aligned} \frac{dL}{dt} &= (I - I_0) \frac{dI}{dt} + \frac{dC}{dt} + \left(\frac{N - N_0}{N}\right) \frac{dN}{dt} \\ &= (I - I_0) \left(\frac{\alpha}{1 + eC} + \frac{p_1 IC}{\beta_1 + C} \right. \\ &\quad - p_2 IC - d_1 I - \alpha + d_1 I_0 \right) \\ &+ \left(m_1 C - m_1 k_1 C^2 - \frac{p_3 IC}{\beta_2 + C} - \gamma_1 CN\right) \\ &+ (N - N_0) \left(m_2 \left(1 - k_2 N\right) - \gamma_2 C\right). \end{aligned}$$

Therefore,

$$\begin{aligned} \frac{dL}{dt} &= (I - I_0) \\ \left( \frac{-\alpha eC}{1 + eC} + \frac{p_1 \ IC}{\beta_1 + C} - p_2 IC - d_1 \left( I - I_0 \right) \right) \\ &+ \left( m_1 C - m_1 k_1 C^2 - \frac{p_3 IC}{\beta_2 + C} - \gamma_1 CN \right) \\ &+ \left( N - N_0 \right) \left( -m_2 k_2 \left( N - N_0 \right) - \gamma_2 C \right). \end{aligned}$$

i.e.,

$$\frac{dL}{dt} = C \left(I - I_0\right) \left(\frac{-\alpha e}{1 + eC} + \frac{p_1 I}{\beta_1 + C} - p_2 I\right) - d_1 \left(I - I_0\right)^2 + \left(m_1 C - m_1 k_1 C^2 - \frac{p_3 IC}{\beta_2 + C} - \gamma_1 CN\right) - m_2 k_2 \left(N - N_0\right)^2 - \gamma_2 C \left(N - N_0\right).$$

$$\implies \frac{dL}{dt} = -\frac{m_1 k_1}{2} C^2 + C \left(I - I_0\right) \\ \left(\frac{-\alpha e}{1 + eC} + \frac{p_1 I}{\beta_1 + C} - p_2 I\right) \\ - d_1 \left(I - I_0\right)^2 - \frac{m_1 k_1}{2} C^2 - \gamma_2 C \left(N - N_0\right) \\ - m_2 k_2 \left(N - N_0\right)^2 \\ + C \left(m_1 - \frac{p_3 I}{\beta_2 + C} - \gamma_1 N\right) \\ \implies \frac{dL}{dt} \le - \left(\sqrt{\frac{m_1 k_1}{2}} C + \sqrt{d_1} \left(I - I_0\right)\right)^2 \\ - \left(\sqrt{\frac{m_1 k_1}{2}} C + \sqrt{m_2 k_2} \left(N - N_0\right)\right)^2$$

$$+ C\left(m_1 - \frac{p_3I}{\beta_2 + C} - \gamma_1N\right)$$

Therefore,  $\frac{dL}{dt} < 0$ , and hence L(t) is a Lyapunov function under condition 10.

Thus, the cancer-free steady state  $A_0$  fulfills the requirements for local stability, rendering the point globally stable. From a biological perspective, chemotherapy refers to the process of selectively eliminating tumor cells if conditions (10) are met.

### 5. Local bifurcation

This section examines the local bifurcation conditions close to steady states by applying Sotomayor's rule for local bifurcation [58, 59].

**Theorem 4.** For  $m_1^* = \frac{p_3\alpha}{\beta_2 d_1} + \frac{\gamma_1}{k_2}$ , the (PSCINC) model, at  $A_0$  has

- No saddle-node bifurcation (SNB).
   A transcritical bifurcation (TB) if
- $(T^{[0]})^T \left[ D^2 h_{m_1} \left( A_0, m_1^* \right) \left( S^{[0]}, S^{[0]} \right) \right] \neq 0.$ (11) (3) A pitchfork bifurcation (PB) if condition (11) is violated where the notation in (11) will be introduced during the proof.

**Proof.** At  $m_1^* = \frac{p_3\alpha}{\beta_2 d_1} + \frac{\gamma_1}{k_2}$ ,  $J(A_0)$  has a zero eigenvalue  $\lambda_2^0 = 0$ . Therefore,  $J(A_0)$  at  $m_1^*$  becomes

$$J^{*}(A_{0}) = \begin{bmatrix} -d_{1} & -e\alpha - \frac{p_{1}\alpha}{\beta_{1}d_{1}} - \frac{p_{2}\alpha}{d_{1}} & 0\\ 0 & 0 & 0\\ 0 & -\frac{\gamma_{2}}{k_{2}} & -m_{2} \end{bmatrix}$$

Now, let  $S^{[0]} = (s_1^{[0]}, s_2^{[0]}, s_3^{[0]})^T$  and  $T^{[0]} = (t_1^{[0]}, t_2^{[0]}, t_3^{[0]})^T$  represent the eigenvectors corresponding to the zero eigenvalue of  $J^*(A_0)$  and  $J^{*T}(A_0)$  respectively. Direct computation gives

$$S^{[0]} = \left(\frac{-(\beta_1 (ed_1 + p_2) + p_1) \alpha}{d_1^2 \beta_1}, 1, \frac{-\gamma_2}{m_2 k_2}\right)^T$$

and

$$T^{[0]} = (0, 1, 0)^T$$

Now, let  $h = (h_1(I, C), h_2(I, C, N), h_3(C, N))^T$ , then differentiating h with respect to  $m_1$  gives:

$$\frac{\partial h}{\partial m_1} = \left(\frac{\partial h_1}{\partial m_1}, \frac{\partial h_2}{\partial m_1}, \frac{\partial h_3}{\partial m_1}\right) = (0, C(1 - k_1 C, 0), h_{m_1}(A_0, m_1^*) = (0, 0, 0).$$

Hence,

$$T^{[0]^T} h_{m_1} (A_0, m_1^*) = (0, 1, 0) (0, 0, 0)^T = 0$$

That means the (SNB) cannot happen at  $m_1^*$ . Subsequently, since

$$T^{[0]^T} h_{m_1} \left( A_0, m_1^* \right) = 0$$

$$T^{[0]T} \left[ Dh_{m_1} \left( A_0, m_1^* \right) S^{[0]} \right] = (0, 1, 0) \begin{bmatrix} 0 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 0 \end{bmatrix}$$
$$\begin{pmatrix} \frac{-(\beta_1(ed_1 + p_2) + p_1) \ \alpha}{d^2 \beta_1} \\ 1 \\ \frac{1}{\frac{-\gamma_2}{m_2 k_2}} \end{pmatrix} = 1 \neq 0$$

$$T^{[0]^{T}}\left[D^{2}h_{m_{1}}\left(A_{0},m_{1}^{*}\right)\left(S^{[0]},S^{[0]}\right)\right]$$

$$=\left(0,1,0\right)\left(2s_{1}^{[0]}\left(\frac{p_{1}\left(1-I_{0}s_{1}^{[0]}\right)}{\beta_{1}}-\left(p_{2}+2e^{2}\alpha s_{1}^{[0]}\right)\right),\frac{p_{3}\left(1+\left(2I_{0}-\beta_{2}\right)\right)}{\beta_{2}^{2}}\right)$$

$$-2\left(m_{1}^{*}k_{1}-\gamma_{1}s_{3}^{[0]}\right),-s_{3}^{[0]}\left(\gamma_{2}+2m_{2}k_{2}s_{3}^{[0]}\right)\right)^{T}$$

$$=\left(\frac{p_{3}\left(1+s_{2}^{[0]}\left(2I_{0}-\beta_{2}\right)\right)}{\beta_{2}^{2}}-2\left(m_{1}^{*}k_{1}-\gamma_{1}s_{3}^{[0]}\right)\right).$$
Therefore, we have a probability of the probabil

This means the required conditions for (TB) are satisfied under condition (11). Finally, if condition (11) is not satisfied, then.

$$\left(T^{[0]}\right)^T D^3 h_{m_1} \left(A_0, m_1^*\right) \left(S^{[0]}, S^{[0]}, S^{[0]}\right) = \frac{2p_3 \left(2\beta_2 s_1^{[0]} - 1 - 3I_0\right)}{\beta_2^3}.$$

Theorem 5. For

$$\gamma_{1}^{*} = \frac{-a_{11}^{[1]^{2}} \left(a_{22}^{[1]} + a_{33}^{[1]}\right) - 2a_{22}^{[1]} a_{33}^{[1]} a_{11}^{[1]}}{C_{1} \left(a_{22}^{[1]} a_{32}^{[1]} + a_{33}^{[1]}\right) + \left(a_{22}^{[1]} a_{33}^{[1]}\right)} - \frac{-a_{22}^{[1]^{2}} \left(a_{11}^{[1]} + a_{33}^{[1]}\right) + \left(a_{11}^{[1]} + a_{22}^{[1]}\right)}{C_{1} \left(a_{22}^{[1]} a_{32}^{[1]} + a_{32}^{[1]} a_{33}^{[1]}\right)} - \frac{\left(-a_{33}^{[1]^{2}} + a_{12}^{[1]} a_{21}^{[1]}\right)}{C_{1} \left(a_{22}^{[1]} a_{32}^{[1]} + a_{32}^{[1]} a_{33}^{[1]}\right)}$$

where  $\gamma_2^* > 0$ , and the formulas of  $a_{ij}^{[2]}$  are given in (8), the (PSCINC) model at  $A_1$  has a (SNB) if

$$(T^{[1]})^T \left[ D^2 h_{\gamma_1} \left( A_1, \gamma_1^* \right) \left( S^{[1]}, S^{[1]} \right) \right] \neq 0$$
 (12)

**Proof.** According to  $J(A_1)$ , given by (6), the (PSCINC) model at  $A_1$  has a zero eigenvalue, say  $\lambda_2^2 = 0$ , at  $\gamma_1^*$  and the Jacobian matrix  $J^*(A_1) = J(A_1, \gamma_1^*)$ , becomes:

$$J^{*}(A_{1}) = \begin{bmatrix} \eta_{11} & \eta_{12} & 0\\ \eta_{21} & \eta_{22} & \eta_{23}\\ 0 & \eta_{32} & \eta_{33} \end{bmatrix},$$

here,

$$\begin{split} \eta_{11} &= \frac{p_1 C_1}{\beta_1 + C_1} - p_2 C_1 - d_1, \\ \eta_{12} &= \frac{-e\alpha}{(1 + eC_1)^2} + \frac{p_1 \beta_1 I_1}{(\beta_1 + C_1)^2} - p_2 I_1, \\ \eta_{21} &= \frac{-p_3}{\beta_2 + C_1}, \\ \eta_{22} &= m_1 - 2m_1 k_1 C_1 - \frac{p_3 \beta_2 I_1}{(\beta_2 + C_1)^2} - \gamma_1^* N_1, \\ \eta_{23} &= -\gamma_1^* C_1, \\ \eta_{32} &= -\gamma_2 N_3, \ \eta_{33} = m_2 - 2m_2 k_2 N_1 - \gamma_2 C_1. \end{split}$$

Now, let

and

$$S^{[1]} = \left(s_1^{[1]}, s_2^{[1]}, s_3^{[1]}\right)^T$$

$$T^{[1]} = \left(t_1^{[1]}, t_2^{[1]}, t_3^{[1]}\right)^T$$

represent the eigenvectors corresponding to the zero eigenvalue of  $J^*(A_1)$  and  $J^{*T}(A_1)$ respectively. Direct computation gives

$$S^{[1]} = \left(\frac{-\eta_{12}}{\eta_{11}}, 1, \frac{-\eta_{32}}{\eta_{33}}\right)^T$$

and

$$T^{[1]} = \left(\frac{-\eta_{21}}{\eta_{11}}, 1, \frac{-\eta_{23}}{\eta_{33}}\right)^{T}$$
  
where  $\eta_{11} \neq 0$  and  $\eta_{33} \neq 0$ .

Subsequently, since

$$T^{[1]^{T}} h_{\gamma_{1}} \left( A_{1}, \gamma_{1}^{*} \right) = \left( \frac{-\eta_{21}}{\eta_{11}}, 1, \frac{-\eta_{23}}{\eta_{33}} \right)$$
$$(0, -C_{1}N_{1}, 0)^{T} = -C_{1}N_{1} \neq 0$$

$$\begin{split} & \left(T^{[1]}\right)^{T} \left[D^{2}h_{\gamma_{1}}\left(A_{1},\gamma_{1}^{*}\right)\left(S^{[1]},S^{[1]}\right)\right] \\ &= \left(\frac{-\eta_{21}}{\eta_{11}},1,\frac{-\eta_{23}}{\eta_{33}}\right) \\ & \left(\frac{2p_{1}\beta_{1}\left(s_{1}^{[1]}-I_{1}s_{2}^{[1]}\right)s_{2}^{[1]}}{\left(\beta_{1}+C_{1}\right)^{2}}-2p_{2}s_{1}^{[1]}s_{2}^{[1]}\right) \\ &+ \frac{2e^{2}\alpha\left(s_{2}^{[1]}\right)^{2}}{\left(1+eC_{1}\right)^{3}},\frac{p_{3}s_{2}^{[1]}\left(s_{2}^{[1]}-s_{1}^{[1]}\beta_{2}\right)}{\left(\beta_{2}+C_{1}\right)^{2}} \\ &+ \frac{2p_{3}\beta_{2}I_{1}\left(s_{2}^{[1]}\right)^{2}}{\left(\beta_{2}+C_{1}\right)^{3}}-2s_{2}^{[1]}\left(\gamma_{1}^{*}+m_{1}k_{1}s_{2}^{[1]},\right) \\ &- \left(s_{2}^{[1]}\gamma_{2}+2m_{2}k_{2}\right)\right)^{T} \\ &= \left(\left(\frac{2p_{1}\beta_{1}\left(s_{1}^{[1]}-I_{1}s_{2}^{[1]}\right)s_{2}^{[1]}}{\left(\beta_{1}+C_{1}\right)^{2}}-2p_{2}s_{1}^{[1]}s_{2}^{[1]}\right) \\ &+ \frac{2e^{2}\alpha\left(s_{2}^{[1]}\right)^{2}}{\left(\beta_{2}+C_{1}\right)^{3}}-\frac{\eta_{21}}{\eta_{11}} \\ &+ \left(\frac{p_{3}s_{2}^{[1]}\left(s_{2}^{[1]}-s_{1}^{[1]}\beta_{2}\right)}{\left(\beta_{2}+C_{1}\right)^{2}}+\frac{2p_{3}\beta_{2}I_{1}\left(s_{2}^{[1]}\right)^{2}}{\left(\beta_{2}+C_{1}\right)^{3}} \\ &-2s_{2}^{[1]}\left(\gamma_{1}^{*}+m_{1}k_{1}s_{2}^{[1]}\right) \\ &- \left(s_{2}^{[1]}\gamma_{2}+2m_{2}k_{2}\right)\left(\frac{-\eta_{23}}{\eta_{33}}\right)\right) \end{split}$$

Hence, condition (12) guarantees that the second condition of saddle-node bifurcation is satisfied. Therefore, the (PSCINC) model has SNB at  $A_1$  with the parameter  $\gamma_1^*$ .

Theorem 6. For

$$\gamma_{2}^{*} = \frac{-a_{11}^{[2]^{2}} \left(a_{22}^{[2]} + a_{33}^{[2]}\right) - a_{22}^{[2]^{2}} \left(a_{11}^{[2]} + a_{33}^{[2]}\right)}{\left(a_{23}^{[2]} a_{33}^{[2]} + a_{22}^{[2]} a_{23}^{[2]}\right) N_{2}} \\ + \frac{\left(a_{11}^{[2]} + a_{22}^{[2]}\right) \left(-a_{33}^{[2]^{2}} + a_{12}^{[2]} a_{21}^{[2]}\right)}{\left(a_{23}^{[2]} a_{33}^{[2]} + a_{22}^{[2]} a_{23}^{[2]}\right) N_{2}} \\ - \frac{2a_{11}^{[2]} a_{22}^{[2]} a_{33}^{[2]}}{\left(a_{23}^{[2]} a_{33}^{[2]} + a_{22}^{[2]} a_{23}^{[2]}\right) N_{2}}$$

where  $\gamma_2^* > 0$ , and the formulas of  $a_{ij}^{[2]}$  are given in (8), the (PSCINC) model at  $A_2$  has a (SNB) if

$$\left(T^{[2]}\right)^{T} \left[D^{2}h_{\gamma_{2}}\left(A_{2},\gamma_{2}^{*}\right)\left(S^{[2]},S^{[2]}\right)\right] \neq 0$$
 (13)

**Proof.** According to  $J(A_2)$ , given by (8), the (PSCINC) model at  $A_2$  has a zero eigenvalue, say  $\lambda_2^3 = 0$ , at  $\gamma_2^*$  and the Jacobian matrix  $J^*(A_2) = J(A_2, \gamma_2^*)$ , becomes:

$$J^{*}(A_{2}) = \begin{bmatrix} \varsigma_{11} & \varsigma_{12} & 0 & \varsigma_{14} \\ \varsigma_{21} & \varsigma_{22} & \varsigma_{23} & \varsigma_{24} \\ 0 & \varsigma_{32} & \varsigma_{33} & 0 \\ 0 & 0 & 0 & \varsigma_{44} \end{bmatrix}$$

$$\varsigma_{11} = \frac{p_{1}C_{2}}{\beta_{1} + C_{2}} - p_{2}C_{2} - d_{1} - d_{2}H_{2},$$

$$\varsigma_{12} = \frac{-e\alpha}{(1 + eC_{2})^{2}} + \frac{p_{1}\beta_{1}I_{2}}{(\beta_{1} + C_{2})^{2}} - p_{2}I_{2},$$

$$\varsigma_{13} = 0,$$

$$\varsigma_{14} = -d_{2}I_{4},$$

$$\varsigma_{21} = \frac{-p_{3}}{\beta_{2} + C_{2}},$$

$$\varsigma_{22} = m_{1} - 2m_{1}k_{1}C_{2} - \frac{p_{3}\beta_{2}I_{2}}{(\beta_{2} + C_{2})^{2}}$$

$$-\gamma_{1}N_{2} - d_{3}H_{2},$$

$$\varsigma_{23} = -\gamma_{1}C_{2},$$

$$\varsigma_{33} = m_{2} - 2m_{2}k_{2}N_{2} - \gamma_{2}^{*}C_{2},$$

$$\varsigma_{44} = -d_{4}.$$

Now, let

 $S^{[2]} = \left(s_1^{[2]}, s_2^{[2]}, s_3^{[2]}, s_4^{[2]}\right)^T$ 

and

$$T^{[2]} = \left(t_1^{[2]}, t_2^{[2]}, t_3^{[2]}, t_4^{[2]}\right)^T$$

represent the eigenvectors corresponding to the zero eigenvalue of  $J^*(A_2)$  and  $J^{*T}(A_2)$ respectively. Direct computation gives

$$S^{[2]} = \left(\frac{\varsigma_{22}\varsigma_{33} - \varsigma_{23}\varsigma_{32}}{\varsigma_{21}\varsigma_{32}}, \frac{-\varsigma_{33}}{\varsigma_{32}}, 1, 0\right)^T$$

and

$$T^{[2]} = \left(\frac{\varsigma_{22}\varsigma_{33} - \varsigma_{23}\varsigma_{32}}{\varsigma_{12}\varsigma_{23}}, \frac{-\varsigma_{33}}{\varsigma_{23}}, \frac{1}{\varsigma_{23}}, \frac{1}{\varsigma_{23}}, \frac{1}{\varsigma_{23}}, \frac{1}{\varsigma_{12}\varsigma_{23}\varsigma_{32} - \varsigma_{22}\varsigma_{33}}{\varsigma_{12}\varsigma_{23}\varsigma_{44}}\right]^{T}$$

where  $\varsigma_{12} \neq 0$ .

$$\begin{split} T^{[2]^{T}}h_{\gamma_{2}}\left(A_{2},\gamma_{2}^{*}\right) &= \left(\frac{\varsigma_{22}\varsigma_{33}-\varsigma_{23}\varsigma_{32}}{\varsigma_{12}\varsigma_{23}},\frac{-\varsigma_{33}}{\varsigma_{23}}, \\ 1, \left[\frac{\varsigma_{14}(\varsigma_{23}\varsigma_{32}-\varsigma_{22}\varsigma_{33})+\varsigma_{12}\varsigma_{33}\varsigma_{24}}{\varsigma_{12}\varsigma_{23}\varsigma_{44}}\right]\right)^{T} \\ &\left((0,0,-C_{2}N_{2},0)^{T}\right)^{T} = -C_{2}N_{2} \neq 0. \\ \left(T^{[2]}\right)^{T} \left[D^{2}h_{\gamma_{2}}\left(A_{2},\gamma_{2}^{*}\right)\left(S^{[2]},S^{[2]}\right)\right] \\ &= \left(\frac{\varsigma_{22}\varsigma_{33}-\varsigma_{23}\varsigma_{32}}{\varsigma_{12}\varsigma_{23}},\frac{-\varsigma_{33}}{\varsigma_{23}}, \\ 1, \left[\frac{\varsigma_{14}(\varsigma_{23}\varsigma_{32}-\varsigma_{22}\varsigma_{33})+\varsigma_{12}\varsigma_{33}\varsigma_{24}}{\varsigma_{12}\varsigma_{23}\varsigma_{44}}\right]\right) \\ &\left(\frac{2p_{1}\beta_{1}(s_{1}^{[2]}-I_{2}s_{2}^{[2]})s_{2}^{[2]}}{(\beta_{1}+C_{2})^{2}} \\ &- 2p_{2}s_{1}^{[2]}s_{2}^{[2]} + \frac{2e^{2}\alpha\left(s_{2}^{[2]}\right)^{2}}{(1+eC_{2})^{3}}, \\ \frac{p_{3}s_{2}^{[2]}(s_{2}^{[2]}-s_{1}^{[2]}\beta_{2})}{(\beta_{2}+C_{2})^{2}} + \frac{2p_{3}\beta_{2}I_{2}\left(s_{2}^{[2]}\right)^{2}}{(\beta_{2}+C_{2})^{3}} \\ &- \left(s_{2}^{[2]}\gamma_{2}^{*}+2m_{2}k_{2}\right), 0\right)^{T} \end{split}$$

$$\begin{split} &= \left( \left( \frac{2p_1\beta_1(s_1^{[2]} - I_2s_2^{[2]})s_2^{[2]}}{(\beta_1 + C_2)^2} \\ &- 2p_2s_1^{[2]}s_2^{[2]} + \frac{2e^2\alpha\left(s_2^{[2]}\right)^2}{(1 + eC_2)^3} \right) \\ &\left( \left( \frac{\varsigma_{22}\varsigma_{33} - \varsigma_{23}\varsigma_{32}}{\varsigma_{12}\varsigma_{23}} \right) + \frac{p_3s_2^{[2]}(s_2^{[2]} - s_1^{[2]}\beta_2)}{(\beta_2 + C_2)^2} \\ &+ \frac{2p_3\beta_2I_2\left(s_2^{[2]}\right)^2}{(\beta_2 + C_2)^3} - 2s_2^{[2]}(\gamma_1 + m_1k_1s_2^{[2]}) \\ &\left( \frac{-\varsigma_{33}}{\varsigma_{23}} \right) - \left( s_2^{[2]}\gamma_2^* + 2m_2k_2 \right) \right). \end{split}$$

Hence, condition (13) guarantees that the second condition of saddle-node bifurcation is satisfied. Therefore, the (PSCINC) model has SNB at  $A_2$  with the parameter  $\gamma_2^*$ .

### 6. Optimal control

This section focuses on analyzing the model following the administration of chemotherapy treatment at a certain time. From a biomedical standpoint, we have included the notion of optimum control in the model. For this purpose, we should look into the problem with a control strategy that can lessen the health hazard for the patient. Therefore, we propose and analyze the optimal control problem applicable to model (PSCINC) to determine the optimal dose of chemotherapy to control the tumor. We decide on control inputs v of cellular chemotherapy, included in the fourth equation of the (PSCINC) model, to be supplied from an external source at different times.

So, let us assume that the time-dependent form of our considered model is given in (1) with the following initial conditions for the model set:

So, let us assume that the time-dependent form of our considered model is given in (1) with the following initial conditions for the (PSCINC) system set:

$$I(0) = I_0, \ C(0) = C_0, N(0) = N_0, H(0) = H_0,$$
(14)

The objective function, which is to be minimized, is defined as follows:

$$\Omega(\tau) = \int_0^{t_f} [I(t) + C(t) + \varepsilon_1 \nu^2(t)] dt, \quad (15)$$

The constants  $\varepsilon_1$  represent the weight factors of the respective terms. These are utilized to equalize the magnitude of the phrases. The ideal selection of control variable  $\nu$  will effectively reduce tumor density and maximize immune density simultaneously, while also minimizing any unfavorable side effects within a set time frame. The initial component of the integrand function represents the overall quantity of tumor cells, the subsequent component of the integrand function represents the overall quantity of immune cells, and the last component of the integrand function indicates the efficacy of the administered medications on the organism. Here, we employ an optimum control problem to the model to minimize the administration of chemotherapeutic drugs, aiming to mitigate side effects and shorten the patient's recovery period. Here, we set up an optimal control  $\nu^*$  such that

$$\Omega\left(\nu^*\right) = \min \{\Omega\left(\nu\right): \nu \in \Delta\}, \qquad (16)$$

where  $\Delta = \{\nu : \text{measurable}, \ 0 \le \nu \le 1, t \in [0, t_f]\}$ is the admissible control set.

### 6.1. The existence of optimal control

In this sub-section, we analyze the existence of an optimal control of the (PSCINC) model (1). The property of super solutions  $\bar{I}, \bar{C}, \bar{N}$ , and  $\bar{H}$  of the model (1) is that trajectories given by

$$\frac{dI}{dt} = \alpha - d_1 \bar{I},$$

$$\frac{d\bar{C}}{dt} = m_1 \bar{C} - p_3 I,$$

$$\frac{d\bar{N}}{dt} = m_2 \bar{N},$$

$$\frac{d\bar{H}}{dt} = \nu - d_4 \bar{H},$$
(17)

are bounded. In vector form, we can express the above system (17) as:

$$\begin{pmatrix} \bar{I} \\ \bar{C} \\ \bar{N} \\ \bar{H} \end{pmatrix}' \leq \begin{pmatrix} -d_1 & 0 & 0 & 0 \\ -p_3 & m_1 & 0 & 0 \\ 0 & 0 & m_2 & 0 \\ 0 & 0 & 0 & -p_4 \end{pmatrix} \begin{pmatrix} \bar{I} \\ \bar{C} \\ \bar{N} \\ \bar{H} \end{pmatrix} + \begin{pmatrix} \alpha \\ 0 \\ 0 \\ \nu \end{pmatrix}$$

Since this is a linear system with bounded coefficients and the time frame is limited, so, we can conclude that the solutions  $\overline{I}$ ,  $\overline{C}$ , $\overline{N}$ , and  $\overline{H}$ , of the above system are bounded. Using the theorem proposed by Lukes [60], we found that the admissible control class and the corresponding state equations with assumed initial conditions are non-empty. Also, by the definition of the set  $\Delta$ , it is clear that the control set  $\Delta$  is convex and closed. Since the state solutions are bounded, hence, the right-hand sides of the state system (1) are continuous and bounded by a sum of the bounded controls and the states.

Now, we examine the convexity of the integrand of  $\Omega(\nu)$  on  $\Delta$  and that it is bounded below by  $\tau_1\nu^2(t) - \tau_2$  with  $\tau_1, \tau_2 > 0$ . Let p, q be distinct elements of  $\Omega$  and  $0 \leq Y \leq 1$ . We have to show that  $\Omega(p_1Y + (1-Y)p_2, q_1Y + (1-Y)q_2) \leq (1-Y)\Omega(p_1, q_1) + Y\Omega(p_2, q_2)$  where,  $\Omega(\nu) = I(t) + C(t) + \varepsilon_1 \nu^2(t)$ ,

To establish it, we proceed as follows:

$$\Omega (p_1 Y + (1 - Y) q_1, p_2 Y + (1 - Y) q_2) - (1 - Y) \Omega (p_1, p_2) + Y \Omega (q_1, q_2) = C (t) + I (t) + \varepsilon_1 (p_1 Y + (1 - Y) q_1)^2 - Y \left\{ C (t) + I (t) + \varepsilon_1 p_1^2 \right\} - (1 - Y) \left\{ C (t) + I (t) + \varepsilon_1 q_1^2 \right\}$$

$$= I(t) + C(t) + \varepsilon_1 (p_1^2 Y^2 + 2p_1 q_1 Y (1 - Y)) + (1 - Y)^2 q_1^2) - Y \left\{ I(t) + C(t) + \varepsilon_1 p_1^2 \right\} - \left\{ I(t) + C(t) + \varepsilon_1 q_1^2 \right\} + Y \left\{ I(t) + C(t) + \varepsilon_1 q_1^2 \right\}$$

$$= \varepsilon_1 p_1^2 Y^2 + 2\varepsilon_1 p_1 q_1 Y (1 - Y) + \varepsilon_1 (1 - Y)^2 q_1^2 - \varepsilon_1 p_1^2 Y - \varepsilon_1 q_1^2 + \varepsilon_1 q_1^2 Y = \varepsilon_1 p_1^2 Y^2 + 2\varepsilon_1 p_1 q_1 Y - 2\varepsilon_1 p_1 q_1 Y^2 + \varepsilon_1 \left(1 - 2Y + Y^2\right) q_1^2 - \varepsilon_1 p_1^2 Y - \varepsilon_1 q_1^2 + \varepsilon_1 q_1^2 Y = \varepsilon_1 p_1^2 Y^2 - 2\varepsilon_1 p_1 q_1 Y^2 + \varepsilon_1 q_1^2 Y^2 - \varepsilon_1 p_1^2 Y + 2\varepsilon_1 p_1 q_1 Y - \varepsilon_1 q_1^2 Y = -\varepsilon_1 (p_2 - q_2)^2 Y (1 - Y) [Since, (Y - 1) < 0, Y - 1]$$

 $= -\varepsilon_1 (p_2 - q_2)^2 Y(1 - Y) \text{ [Since, } (Y - 1) \le 0.$ and if  $\varepsilon_1 \ge 0$ ], and

$$I(t) + C(t) + \varepsilon_1 \nu^2(t) \ge \varepsilon_1 \nu^2(t) \ge \tau_1 \nu^2(t)$$
$$\ge \tau_1 \nu^2(t) - \tau_2.$$

This shows that  $\tau_1 \nu^2(t) - \tau_2$  is a lower bound of  $\Omega(\tau, \mu)$ . This verifies that there exists an optimal control  $\nu^*$  for which  $\Omega(\nu^*) = \min \Omega(\nu^*) =$  $\min \{\Omega(\nu) : \nu \in \Delta\}$  From the above analysis and conclusion, we state the following theorem.

**Theorem 7.** Subject to the system (1), with initial conditions  $I(0) = I_0, C(0) = C_0, N(0) = N_0, and H(0) = \nu_0$ , the objective functional

$$\Omega(\nu) = \int_0^{t_f} \left[ I(t) + C(t) + \varepsilon_1 \nu^2(t) \right] dt$$

admits an optimal control  $\nu^*$  such that  $\Omega(\nu^*) = \min\{\Omega(\nu) : \nu \in \Delta\}$ , where  $\Delta = (\nu)\nu$  are piecewise continuous,  $0 \leq \nu \leq 1, t \in [0, t_f]$ .

# 6.2. Characterization of the optimal control

For applying the Pontryagin maximum principle [46], we introduced the four co-state variables

 $\xi_i$  (i = 1, 2, 3, 4). The Hamiltonian function is given by

$$h = I + C + \varepsilon_1 \nu^2 + \xi_1 \dot{I} + \xi_2 \dot{C} + \xi_3 \dot{N} + \xi_4 \dot{H} \quad (18)$$

With substitution from (1) into (18), we get

$$\begin{aligned} h* &= I + C + \varepsilon_1 \nu^2 \\ \xi_1 \left( \frac{\alpha}{1 + eC} + \frac{p_1 \ IC}{\beta_1 + C} - p_2 IC - d_1 I - d_2 IH \right) \\ &+ \xi_2 \left( m_1 C \left( 1 - k_1 C \right) - \frac{p_3 IC}{\beta_2 + C} - \gamma_1 CN - d_3 HC \right) \\ &+ \xi_3 \left( m_2 N \left( 1 - k_2 N \right) - \gamma_2 CN \right) + \xi_4 \left( \nu - d_4 H \right), \end{aligned}$$

The Hamiltonian equations are:

$$\dot{\xi}_1 = -\frac{\partial h^*}{\partial I}, \dot{\xi}_2 = -\frac{\partial h^*}{\partial C}, \dot{\xi}_3 = -\frac{\partial h^*}{\partial N}, \dot{\xi}_4 = -\frac{\partial h^*}{\partial H},$$
(19)

where,  $\xi_i(t)$ , i = 1, 2, 3, 4 are the adjoint functions to be determined suitably.

The form of the adjoint equations and transversality conditions are standard results from Pontryagin's Maximum Principle [61]. The adjoint system can be written in the form:

$$\begin{split} \dot{\xi}_{1} &= -\frac{\partial h*}{\partial I} \\ &= -1 - \xi_{1} \left( \frac{p_{1}C}{\beta_{1} + C} - p_{2}C - d_{1} - d_{2}H \right) \\ &+ \xi_{2} \frac{p_{3}IC}{\beta_{2} + C}, \\ \dot{\xi}_{2} &= -\frac{\partial h*}{\partial C} \\ &= -1 + \xi_{1} \left( \frac{-e\alpha}{(1 + eC)^{2}} + \frac{p_{1}\beta_{1}I}{(\beta_{1} + C)^{2}} - p_{2}I \right) \\ &- \xi_{2} (m_{1} - 2Cm_{1}k_{1} - \frac{p_{3}\beta_{2}I}{(\beta_{2} + C)^{2}} - \gamma_{1}N - d_{3}H) \\ &+ \xi_{3}\gamma_{2}N, \end{split}$$

$$\begin{aligned} \dot{\xi}_3 &= -\frac{\partial h^*}{\partial N} \\ &= \xi_2 \gamma_1 C - \xi_3 \left( m_2 - 2m_2 k_2 N - \gamma_2 C \right), \\ \dot{\xi}_4 &= -\frac{\partial h^*}{\partial H} = \xi_1 d_2 I + \xi_2 d_3 C + d_4 \xi_4, \end{aligned}$$

The transversality conditions are  $\xi_i(t_f) = 0$ , for i = 1, 2, 3, 4.

The condition dictate the necessary optimum control functions is

$$\frac{\partial h*}{\partial \nu} = 0.$$

Hence, we get

$$\nu^{*}(t) = -\frac{\xi_{4}}{2\varepsilon_{1}}; \nu = \nu^{*}(t)$$
 (20)

By using the bounds for the control  $\nu^*(t)$  from (20), we get

$$\nu^* = \begin{cases} -\frac{\xi_4}{2\varepsilon_1}, & if \ 0 \ \le -\frac{\xi_4}{2\varepsilon_1} \le 1\\ 0, & if \ -\frac{\xi_4}{2\varepsilon_1} \le 0\\ 1, & if \ \frac{\xi_4}{2\varepsilon_1} \ge 1 \end{cases}$$

In compact notation, we have

$$\nu^* = \min\left\{\max\left\{0, -\frac{\xi_4}{2\varepsilon_1}\right\}, 1\right\}, \qquad (21)$$

Based on the analysis and conclusion presented above, the subsequent theorem is derived.

**Theorem 8.** For optimal control  $\nu^*$ and corresponding state variable solutions  $I^*(t), C^*(t), N^*(t)$  and  $H^*(t)$  that minimize over  $\Delta$ , there exist specific adjoint variables  $\xi_i(t)$ , i = 1, 2, 3, 4 satisfying the following system:

$$\dot{\xi}_{1} = -1 - \xi_{1} \left( \frac{p_{1} C}{\beta_{1} + C} - p_{2}C - d_{1} - d_{2}H \right) + \xi_{2} \frac{p_{3}IC}{\beta_{2} + C}, \dot{\xi}_{2} = -1 + \xi_{1} \left( \frac{-e\alpha}{(1 + eC)^{2}} + \frac{p_{1} \beta_{1}I}{(\beta_{1} + C)^{2}} - p_{2}I \right) - \xi_{2} (m_{1} - 2Cm_{1}k_{1} - \frac{p_{3}\beta_{2}I}{(\beta_{2} + C)^{2}} - \gamma_{1}N - d_{3}H) + \xi_{3}\gamma_{2}N, \dot{\xi}_{3} = \xi_{2}\gamma_{1}C - \xi_{3} (m_{2} - 2m_{2}k_{2}N - \gamma_{2}C), \quad (22) \dot{\xi}_{4} = \xi_{1}d_{2}I + \xi_{2}d_{3}C + d_{4}\xi_{4},$$

subject to the transversality conditions

$$\xi_i(t_f) = 0, \ i = 1, 2, 3, 4.$$

Furthermore, the subsequent properties are valid:

$$\tau^* = \min\left\{\max\left\{0, -\frac{\xi_4}{2\varepsilon_1}\right\}, 1\right\}$$

### 7. Numerical Analysis

Numerical verification is essential for completing analytical studies. In this section, we visually confirmed the accuracy of our analytical findings for the (PSCINC) system using the software MATLAB. This verification holds significant practical significance. The simulations were conducted using the parameter values specified below [53].

$$\begin{aligned} \alpha = & 0.05, \ e = 0.1, p_1 = 0.1, \beta_1 = 0.4, p_2 = 0.2, \\ d_1 = & 0.2, d_2 = 0.09, m_1 = 0.4, \ k_1 = 1.5, \\ p_3 = & 0.3, \beta_2 = 0.4, \ \gamma_1 = & 0.2, d_3 = 0.05, \\ m_2 = & 0.35, k_2 = 1; \gamma_2 = & 0.25, \nu = & 0.019, \\ d_4 = & 0.05. \end{aligned}$$

Now, we will consider five scenarios to comprehend the dynamic behavior of the (PSCINC) model and assess the influence of chemotherapy treatment and psychological anxiety on tumor suppression. Subsequently, the outcomes of the five cases will be juxtaposed for comparison. The five cases are:

### 7.1. Case I: the healthy case

In this scenario, we examine the interaction dynamics between healthy cells N(t) and immune cells I(t) in the absence of chemotherapy treatment and psychological nervousness, i.e., where  $\nu = 0$  and e = 0. Figure 2 depicts the (PSCINC) model with a cancer-free equilibrium point and a single positive equilibrium at  $A_0 =$ (2, 0, 2.38, 0) Furthermore, regardless of the initial values, the solution initially experiences growth or decline before converging asymptotically to  $A_0$ after approximately thirty days.



### and e = 0.

### 7.2. Case II: no treatment case

Here, we examine the behavior of the (PSCINC) model in the absence of treatment and the psychological scare. Figure 3 illustrates the performance of the (PSCINC) model where  $\nu = 0$ and e = 0. All initial conditions lead to the convergence of the system to a treatment-free equilibrium point  $A_1 = (I_1, C_1, N_1, 0) =$ (0.25, 0.13, 0.9, 0). In addition, the population of immune cells steadily diminishes as the number of tumor cells gradually increases. Furthermore, this case clearly demonstrates that eradicating tumor cells is unattainable without a well-defined therapeutic strategy.



Figure 3. The dynamics of the (PSCINC) model with  $\nu = 0$  and e = 0.

### 7.3. Case III: psychological scare case

The objective of this case is to demonstrate the impact of anxiety on the interaction between cancer cells and immune cells in the absence of chemotherapy drugs. Figure 4 explains the performance of the (PSCINC) model where  $\nu = 0$  with various values of e. The relationship between rising anxiety and declining immune function is evident. As a result, the tumor cells significantly grow; therefore, external treatment is needed.



**Figure 4.** The dynamics of the (PSCINC) model with  $\nu = 0$  and various value of e.

#### 7.4. Case IV: a treatment case

In this instance, we will examine the intricacies the (PSCINC) system when subjected of chemo-drug. Figure.5 clearly depicts  $\mathrm{to}$ the global stability characteristics of the positive steady state  $A_2 = (I_2, C_2, N_2, H_2) =$ The administration of (0.2, 0.14, 0.89, 0.38).chemotherapy leads to a substantial decrease in tumor cells within the body compared to past instances. In addition, chemotherapy also adversely affects the immune cells, decreasing the quantity of immune cells compared to the previous cases. Considering those mentioned above, additional doses are necessary to achieve a state devoid of tumors.



Figure 5. The dynamics of the (PSCINC) model with treatment case.

## 7.5. Case V: a minimum dosage of chemo-drug

This case aims to examine the effects of modifying the number of chemotherapy doses required to achieve a healthy state. Figure 5 clarifies the performance of the (PSCINC) model with various values of  $\nu$ . The solution of the (PSCINC) system asymptotically converges to  $A_2$  when v is less than 0.14. Conversely, the system tends towards a cancer-free state  $A_0$  when  $\nu = 0.14$ . Thus, a value of  $\nu = 0.14$  is the minimum dosage of chemotherapy necessary to achieve a condition devoid of cancer.



Figure 6. The dynamics of the (PSCINC) model with various values of  $\nu$ 

### 8. Conclusion

It has been looked at how an ODE mathematical model for tumor growth works, which includes how immune cells interact with tumor cells and how psychological scares and chemotherapy drugs work. The fundamental attributes of the model's solutions, including positivity and boundedness, were established. A stability analysis was conducted on the system under consideration to investigate the model's dynamic behavior. Our research indicates that the constant state devoid of tumors is stable globally under particular conditions. This suggests that the prescribed treatment can eliminate tumor cells from the body for a specific tumor growth rate.

The numerical simulations validate the analytical findings. Precisely, the threshold values for the transcritical bifurcation are calculated, indicating the point at which cancer transitions from persisting to eradicating. Additionally, numerical analysis reveals that when the tumor size is modest, the prescribed chemotherapy drug can effectively eliminate tumor cells from the body with a minimal minimum dose. Nonetheless, a constraint of our model is that prolonged treatment and a substantial dosage of medications are necessary to eradicate large tumors, both of which can be detrimental to the patient's health.

Our upcoming research will focus on augmenting the immune system by regular vitamin intake or the utilization of stem cells.

### References

- Gershenfeld, N. A. (1999). The nature of mathematical modeling. Cambridge university press, Cambridge, United Kingdom.
- [2] Thirthar, A. A. (2023). A mathematical modelling of a plant-herbivore community with additional effects of food on the environment. *Iraqi Journal of Science*, 64(7), 3551-3566.
- [3] Murray, J. D. (2002). Models for Interacting Populations. In: J. D. Murray, ed., *Mathematical Biology: I. An Introduction*. Springer, New York, 79-118. https://doi.org/10.1007/978-0-387 -22437-4\_3
- [4] Murray, J. D. (2002). Continuous Population Models for Single Species. In: J. D. Murray, eds., *Mathematical Biology: I. An Introduction*. Springer, New York, 1-43. https://doi.org/10 .1007/978-0-387-22437-4\_1
- [5] Shalan, R. N., Shireen, R., & Lafta, A. H. (2021). Discrete an SIS model with immigrants and treatment. *Journal of Interdisciplinary Mathematics*, 24(5), 1201-1206. https://doi. org/10.1080/09720502.2020.1814496
- [6] Sk, N., Mondal, B., Thirthar, A. A., Alqudah, M. A., & Abdeljawad, T. (2023). Bistability and tristability in a deterministic prey-predator model: Transitions and emergent patterns in its stochastic counterpart. *Chaos, Solitons & Fractals*, 176, 114073. https://doi.org/10.1 016/j.chaos.2023.114073
- [7] Chatterjee, A., & Pal, S. (2023). A predator-prey model for the optimal control of fish harvesting

through the imposition of a tax. An International Journal of Optimization and Control: Theories & Applications (IJOCTA), 13(1), 68-80. https: //doi.org/10.11121/ijocta.2023.1218

- [8] Sene, N. (2022). Theory and applications of new fractional-order chaotic system under Caputo operator. An International Journal of Optimization and Control: Theories & Applications (IJOCTA), 12(1), 20-38. https: //doi.org/10.11121/ijocta.2022.1108
- [9] Hoang, M. T., Ngo, T. K. Q., & Truong, H. H. (2023). A simple method for studying asymptotic stability of discrete dynamical systems and its applications. An International Journal of Optimization and Control: Theories & Applications (IJOCTA), 13(1), 10-25. https: //doi.org/10.11121/ijocta.2023.1243
- [10] Courchamp, F., Berec, L., & Gascoigne, J. (2008). Allee effects in ecology and conservation. OUP Oxford, Oxford, England. https://doi.org/10 .1093/acprof:oso/9780198570301.001.0001
- [11] Allee, W. C., & Bowen, E. S. (1932). Studies in animal aggregations: mass protection against colloidal silver among goldfishes. *Journal of Experimental Zoology*, 61(2), 185-207. https: //doi.org/10.1002/jez.1400610202
- [12] Gómez-Llano, M., Germain, R. M., Kyogoku, D., McPeek, M. A., & Siepielski, A. M. (2021). When ecology fails: how reproductive interactions promote species coexistence. *Trends in Ecology & Evolution*, 36(7), 610-622. https://doi.org/10 .1016/j.tree.2021.03.003
- [13] Jawad, S., Sultan, D., & Winter, M. (2021). The dynamics of a modified Holling-Tanner prey-predator model with wind effect. *International Journal of Nonlinear Analysis* and Applications, 12(Special Issue), 2203-2210.
- [14] Al Nuaimi, M., & Jawad, S. (2022). Modelling and stability analysis of the competitional ecological model with harvesting. *Communications in Mathematical Biology and Neuroscience*, 2022, 1-29.
- [15] Hassan, S. K., & Jawad, S. R. (2022). The Effect of Mutual Interaction and Harvesting on Food Chain Model. *Iraqi Journal of Science*, 63(6), 2641-2649. https://doi.org/10.24996/ijs.2 022.63.6.29
- [16] Dawud, S., & Jawad, S. (2022). Stability analysis of a competitive ecological system in a polluted environment. *Communications in Mathematical Biology and Neuroscience*, 2022, 1-34.
- [17] Hollingsworth, Τ. D. (2009).Controlling infectious disease outbreaks: Lessons from mathematical modelling. Journal public328-341. ofhealth policy, 30,https://doi.org/10.1057/jphp.2009.13
- [18] White, P. J., & Enright, M. C. (2010). Mathematical models in infectious disease epidemiology. *Infectious Diseases*, 70-75. https://doi.org/10.1016/B978-0-323 -04579-7.00005-8

- [19] Huppert, A., & Katriel, G. (2013). Mathematical modelling and prediction in infectious disease epidemiology. *Clinical Microbiology and Infection*, 19(11), 999-1005. https://doi.org/10.1111/14 69-0691.12308
- [20] Kareem, A. M., & Al-Azzawi, S. N. (2021). A stochastic differential equations model for the spread of coronavirus COVID-19): the case of Iraq. *Iraqi Journal of Science*, 63(3), 1025-1035. https://doi.org/10.24996/ijs.2021.62.3.3
- [21] Hameed, H. H., & Al-Saedi, H. M. (2021). Three-Dimensional Nonlinear Integral Operator with the Modelling of Majorant Function. Baghdad Science Journal, 18(2), 0296-0296. http s://doi.org/10.21123/bsj.2021.18.2.0296
- [22] Kareem, A. M., & Al-Azzawi, S. N. (2022). Comparison Between Deterministic and Stochastic Model for Interaction (COVID-19) With Host Cells in Humans. Baghdad Science Journal, 19(5), 1140-1140. https://doi.org/10.21123/bsj.2022.6111
- [23] Kirschner, D., & Panetta, J. C. (1998). Modeling immunotherapy of the tumor-immune interaction. Journal of Mathematical Biology, 37, 235-252. https://doi.org/10.1007/s002850050127
- [24] Frascoli, F., Kim, P. S., Hughes, B. D., & Landman, K. A. (2014). A dynamical model of tumour immunotherapy. *Mathematical Biosciences*, 253, 50-62. https://doi.org/10.1 016/j.mbs.2014.04.003
- [25] Villasana, M., & Radunskaya, A. (2003). A delay differential equation model for tumor growth. *Journal of Mathematical Biology*, 47, 270-294. ht tps://doi.org/10.1007/s00285-003-0211-0
- [26] Huang, M., Liu, S., Song, X., & Zou, X. (2022). Control strategies for a tumor-immune system with impulsive drug delivery under a random environment. Acta Mathematica Scientia, 42(3), 1141-1159. https://doi.org/10.1007/s10473 -022-0319-1
- [27] Saeed, T., Djeddi, K., Guirao, J. L., Alsulami, H. H., & Alhodaly, M. S. (2022). A discrete dynamics approach to a tumor system. *Mathematics*, 10(10), 1774. https://doi.org/10.3390/math 10101774
- [28] Iarosz, K. C., Borges, F. S., Batista, A. M., Baptista, M. S., Siqueira, R. A., Viana, R. L., & Lopes, S. R. (2015). Mathematical model of brain tumour with glia-neuron interactions and chemotherapy treatment. *Journal of Theoretical Biology*, 368, 113-121. https://doi.org/10.101 6/j.jtbi.2015.01.006
- [29] Colli, P., Gilardi, G., & Sprekels, J. (2019). A distributed control problem for a fractional tumor growth model. *Mathematics*, 7(9), 792. https: //doi.org/10.3390/math7090792
- [30] Alharbi, S. A., & Rambely, A. S. (2020). A new ODE-based model for tumor cells and immune system competition. *Mathematics*, 8(8), 1285. ht tps://doi.org/10.3390/math8081285

- [31] Ghanbari, B. (2020). On the modeling of the interaction between tumor growth and the immune system using some new fractional and fractional-fractal operators. Advances in Difference Equations, 2020(1), 1-32. https://do i.org/10.1186/s13662-020-03040-x
- [32] Arshad, S., Yıldız, T. A., Baleanu, D., & Tang, Y. (2020). The role of obesity in fractional order tumor-immune model. *Politehn. Univ. Bucharest Sci. Bull. Ser. A Appl. Math. Phys*, 82(2), 181-196.
- [33] Akman Yıldız, T., Arshad, S., & Baleanu, D. (2018).Optimal chemotherapy and immunotherapy schedules for a cancer-obesity model with Caputo time fractional derivative. Mathematical Methods intheApplied Sciences, 41(18),9390-9407. https://doi.org/10.1002/mma.5298
- [34] Alqudah, M. A. (2020). Cancer treatment by stem cells and chemotherapy as a mathematical model with numerical simulations. *Alexandria Engineering Journal*, 59(4), 1953-1957. https: //doi.org/10.1016/j.aej.2019.12.025
- [35] Jawad, S., Winter, M., Rahman, Z. A. S., Al-Yasir, Y. I., & Zeb, A. (2023). Dynamical behavior of a cancer growth model with chemotherapy and boosting of the immune system. *Mathematics*, 11(2), 406. https://doi. org/10.3390/math11020406
- [36] Letellier, C., Sasmal, S. K., Draghi, C., Denis, F., & Ghosh, D. (2017). A chemotherapy combined with an anti-angiogenic drug applied to a cancer model including angiogenesis. *Chaos, Solitons & Fractals*, 99, 297-311. https://doi.org/10.101 6/j.chaos.2017.04.013
- [37] De Pillis, L. G., & Radunskaya, A. (2001). A mathematical tumor model with immune resistance and drug therapy: an optimal control approach. Computational and Mathematical Methods in Medicine, 3(2), 79-100. https: //doi.org/10.1080/10273660108833067
- [38] De Pillis, L. G., Gu, W., & Radunskaya, A. E. (2006). Mixed immunotherapy and chemotherapy of tumors: modeling, applications and biological interpretations. *Journal of Theoretical Biology*, 238(4), 841-862. https://doi.org/10.1016/j.jtbi.2005.06.037
- [39] Suraci, J. P., Clinchy, M., Dill, L. M., Roberts, D., & Zanette, L. Y. (2016). Fear of large carnivores causes a trophic cascade. *Nature Communications*, 7(1), 10698. https://doi.or g/10.1038/ncomms10698
- [40] Pal, S., Pal, N., Samanta, S., & Chattopadhyay, J. (2019). Effect of hunting cooperation and fear in a predator-prey model. *Ecological Complexity*, 39, 100770. https://doi.org/10.1016/j.ecoc om.2019.100770
- [41] Sarkar, K., & Khajanchi, S. (2020). Impact of fear effect on the growth of prey in a predator-prey interaction model. *Ecological Complexity*, 42,

100826. https://doi.org/10.1016/j.ecocom .2020.100826

- [42] He, M., & Li, Z. (2022). Stability of a fear effect predator-prey model with mutual interference or group defense. *Journal of Biological Dynamics*, 16(1), 480-498. https://doi.org/10.1080/17 513758.2022.2091800
- [43] Yousef, A., Thirthar, A. A., Alaoui, A. L., Panja, P., & Abdeljawad, T. (2022). The hunting cooperation of a predator under two prey's competition and fear-effect in the prey-predator fractional-order model. *AIMS Mathematics*, 7(4), 5463-5479. https://doi.org/10.3934/math.2 022303
- [44] Thirthar, A. A., Abboubakar, H., Khan, A., & Abdeljawad, T. (2023). Mathematical modeling of the COVID-19 epidemic with fear impact. *AIMS Mathematics*, 8(3), 6447-6465. https://doi.or g/10.3934/math.2023326
- [45] Doshi, D., Karunakar, P., Sukhabogi, J. R., Prasanna, J. S., & Mahajan, S. V. (2021). Assessing coronavirus fear in Indian population using the fear of COVID-19 scale. *International Journal of Mental Health and Addiction*, 19, 2383-2391. https://doi.org/10.1007/s11469 -020-00332-x
- [46] Gormley, M., Knobf, M. T., Vorderstrasse, A., Aouizerat, B., Hammer, M., Fletcher, J., & D'Eramo Melkus, G. (2021). Exploring the effects of genomic testing on fear of cancer recurrence among breast cancer survivors. *Psycho-Oncology*, 30(8), 1322-1331. https://doi.org/10.1002/po n.5679
- [47] Niknamian, S. (2019). The impact of stress, anxiety, fear and depression in the cause of cancer in humans. American Journal of Biomedical Science and Research, 3(4), 363-370. https:// doi.org/10.34297/AJBSR.2019.03.000696
- [48] Epstein, J. M., Parker, J., Cummings, D., & Hammond, R. A. (2008). Coupled contagion dynamics of fear and disease: mathematical and computational explorations. *PloS One*, 3(12), e3955. https://doi.org/10.1371/journal. pone.0003955
- [49] Vrinten, C., McGregor, L. M., Heinrich, M., von Wagner, C., Waller, J., Wardle, J., & Black, G. B. (2017). What do people fear about cancer? A systematic review and meta-synthesis of cancer fears in the general population. *Psycho-Oncology*, 26(8), 1070-1079. https://doi.org/10.1002/po n.4287
- [50] Lebel, S., Tomei, C., Feldstain, A., Beattie, S., & McCallum, M. (2013). Does fear of cancer recurrence predict cancer survivors' health care use?. Supportive Care in Cancer, 21, 901-906. ht tps://doi.org/10.1007/s00520-012-1685-3
- [51] de Pillis, L. G., & Radunskaya, A. (2003). -A mathematical model of immune response to tumor invasion. In: K. J. Bathe, ed., *Computational Fluid and Solid Mechanics.*

Elsevier Science Ltd, 1661-1668. https://doi. org/10.1016/B978-008044046-0.50404-8

- [52] Wang, X., Zanette, L., & Zou, X. (2016). Modelling the fear effect in predator-prey interactions. Journal of Mathematical Biology, 73(5), 1179-1204. https://doi.org/10.1007/ s00285-016-0989-1
- [53] Das, A., Dehingia, K., Ray, N., & Sarmah, H. K. (2023). Stability analysis of a targeted chemotherapy-cancer model. *Mathematical Modelling and Control*, 3(2), 116-126. https://doi.org/10.3934/mmc.2023011
- [54] Hubbard, J. H., & West, B. H. (2012). Differential equations: a dynamical systems approach: higher-dimensional systems. Vol. 18. Springer Science & Business Media, New York.
- [55] Perko, L. (2013). Differential equations and dynamical systems. Vol. 7. Springer Science & Business Media, New York.
- [56] Hirsch, M. W., Smale, S., & Devaney, R. L. (2012). Differential equations, dynamical systems, and an introduction to chaos. Academic press, New York. https://doi.org/10.1016/B978 -0-12-382010-5.00015-4
- [57] Place, C. M. (2017). Dynamical Systems: Differential Equations, Maps, and Chaotic Behaviour. Routledge, London.
- [58] Jawad, S. R., & Al Nuaimi, M. (2023). Persistence and bifurcation analysis among four species interactions with the influence of competition, predation and harvesting. *Iraqi Journal of Science*, 64(3) 1369-1390. https://doi.org/10 .24996/ijs.2023.64.3.30
- [59] Jawad, S., & Hassan, S. K. (2023). Bifurcation analysis of commensalism intraction and harvisting on food chain model. Brazilian Journal of Biometrics, 41(3), 218-233. https://doi.org/10.28951/bjb.v41i3.609
- [60] Lukes, D. L. (1969). Optimal regulation of nonlinear dynamical systems. SIAM Journal on Control, 7(1), 75-100. https://doi.org/10.113 7/0307007
- [61] Kopp, R. E. (1962). Pontryagin Maximum Principle. In: G. Leitmann, ed., Mathematics in Science and Engineering. Elsevier, 255-279. https://doi.org/10.1016/S0076-5392(08)6 2095-0

Rafel Ibrahim Salih Bachelor in applied science in department of mathematics, university of technology, Teacher at ministry of education - Second Karkh Education Directorate - Al-Suwaib Girls Secondary School, Teacher at ministry of education - Second Karkh Education Directorate - Al-Nafi Secondary School, Student M.Sc in applied mathematics science at university of Baghdad from 2022/9/4 and present. https://orcid.org/0009-0004-4706-6979

Shireen Jawad is a faculty member of the University of Baghdad, College of Science. She graduated from the University of Baghdad, College of Science, Department of Mathematics, in 2005. Then she received her PhD in applied mathematics-dynamical systems from Brunel University, London. Her research interest is mathematical modeling and analysis of dynamical systems.

https://orcid.org/0000-0002-3090-8357

Kaushik Dehingia obtained his PhD in Mathematical Biology and Dynamical Systems from Gauhati University, Guwahati, India, MSc from Tezpur University, Tezpur, India. Currently, he is working as an Assistant Professor at Sonari College, Sonari, India. His research interests are in the areas of Mathematical Modeling, Dynamical Systems, Mathematical Biology and Nonlinear Dynamics. https://orcid.org/0000-0002-8042-4166

Anusmita Das received her PhD in Mathematical Biology and Dynamical Systems from Gauhati University, Guwahati, India, MSc from Gauhati University, Guwahati, India. Currently, she is working as an Assistant Professor at Udalguri College, Udalguri, India. Her research interests are in the areas of Mathematical Modeling, Dynamical Systems and Mathematical Biology.

https://orcid.org/0000-0003-4022-8053

An International Journal of Optimization and Control: Theories & Applications (http://www.ijocta.org)



This work is licensed under a Creative Commons Attribution 4.0 International License. The authors retain ownership of the copyright for their article, but they allow anyone to download, reuse, reprint, modify, distribute, and/or copy articles in IJOCTA, so long as the original authors and source are credited. To see the complete license contents, please visit http://creativecommons.org/licenses/by/4.0/.